2024 CHiP Annual Meeting

The New AS GW Laboratory – Status and Plans

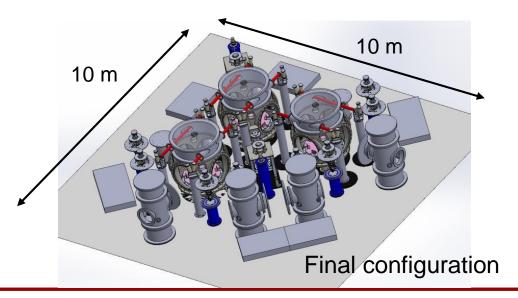
Cheng-Han Chan, Kun-Yao Chang, Dong-Yu Chen, **Hsiang-Chieh Hsu**, Hsiang-yu Huang, Yoyo Huang, You-Ru Lee, Feng-Kai Lin, Chien-Yu Lin, Yi-Shong Lin, Miftahul Ma'arif, Avani Patel, Daiki Tanabe, Vivek Kumar, Chun-Huan Wang, Zi-Yu Wang, Dennis Yu

> Prof. Henry Tsz-King Wong, Prof. Yuki Inoue, Prof. Shiuh Chao ASGRAF team 2024/11/20



The New AS GW Laboratory

- Academia Sinica GRAvitational research Facility (ASGRAF)
- IOP B1 $10 \times 10 m^2$, Clean Room Spec @ C-10000
- Menu (plan)
 GW "System" Test Facility
 Cryo & Mirror & AVIS Research
 Move NTHU Lab
 Future CHRONOS prototype



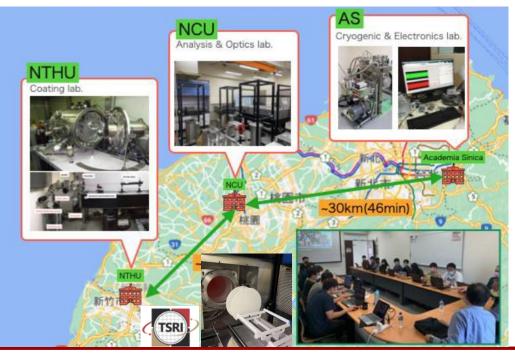






Group member

- Collaboration team: AS + NCU + NTHU
- Prof. Chao retired after Jul. 2024
 Move to ASGRAF
- A new gas line was built for LPCVD SiON fabrication in TSRI (Kun-Yao Chang's report). NCU



- Henry Tsz-King Wong
- Feng-Kai Lin
- Daiki Tanabe
- Hsiang-Chieh Hsu
- Vivek Kumar

Yuki Inoue

Avani Patel

You-Ru Lee

Yi-Shong Lin

Dennis Yu

Yoyo Huang

Hsiang-yu huang

Cheng-Han Chan Kun-Yao Chang

Miftahul Ma'arif

NTHU

- Shiuh Chao 趙煦 (Retired)
- Chien-Yu Lin (Grad.)
- Chun-Huan Wang (Grad.)
- Dong-Yu Chen (Grad.)
- Zi-Yu Wang (Grad.)



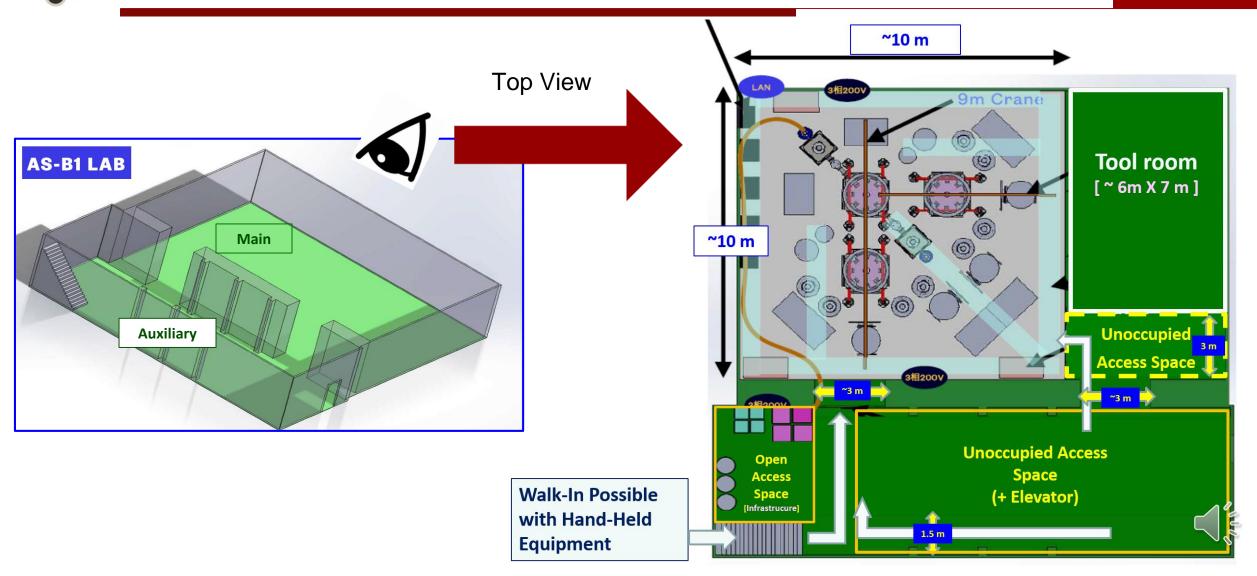


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AS



Construction: Lab design schematic



ASGRAF



TIMELINE



2022/09: Clean old Lab



2023/01: construction

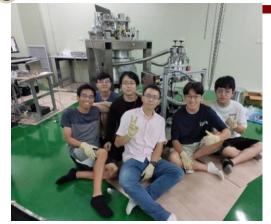


2023/03: clean room finish & testing

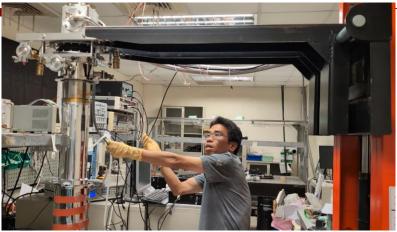








2024/05: moving instrument into Lab



2024/10: moving NTHU Lab











Status now



Now (Nov. 2024)

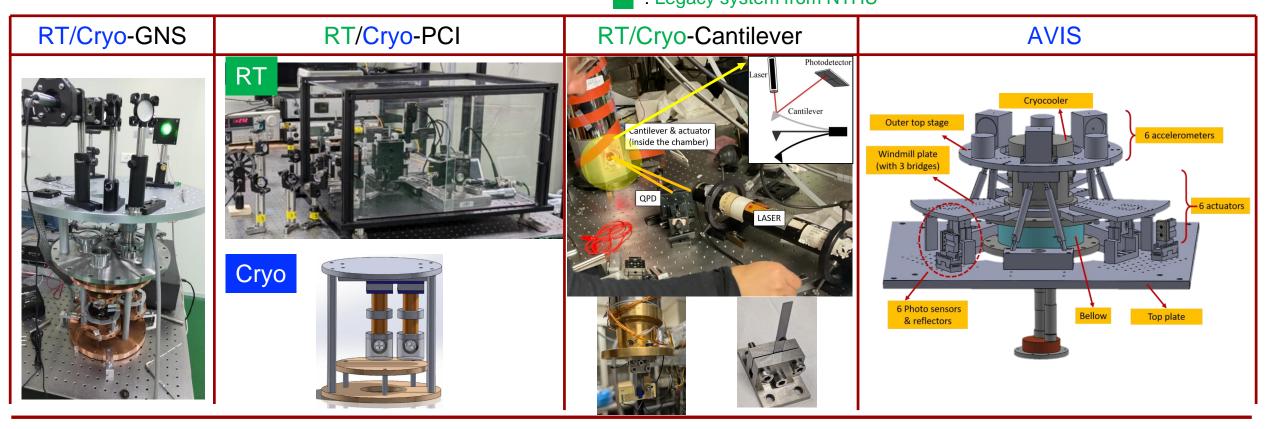
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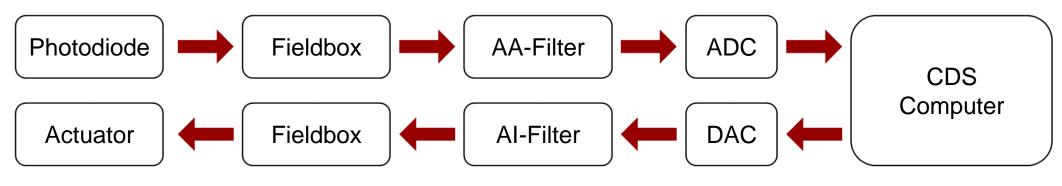
Loss measurement: 3 Machine (Cantilever, GNS, PCI) * 2 version (RT/Cryo): 6 in total

(GNS: Gentle Noodle Suspension; PCI: Photothermal Common-path Interferometry)

- Active Vibration Isolation System (AVIS)
- : Newly developed system : Legacy system from NTHU



- Many sensors and actuators: Control and Data System (CDS) by LIGO
- **Hardware**: To form multiple-input multiple-output control loops
- DAC, ADC
- □ PCIe extension board, I/O board and timing board connecting with Standalone system
- □ AA and AI filters
- Software: based on a real-time enabled Linux operating system
 - Experimental Physics and Industrial Control System (EPICS): operators control screens and channel access
 - □ Matlab/Simulink tools: workflow for a digital control circuit.
 - Creating a real-time kernel module from this circuit model by Matlab/Simulink, and control the module via EPICS

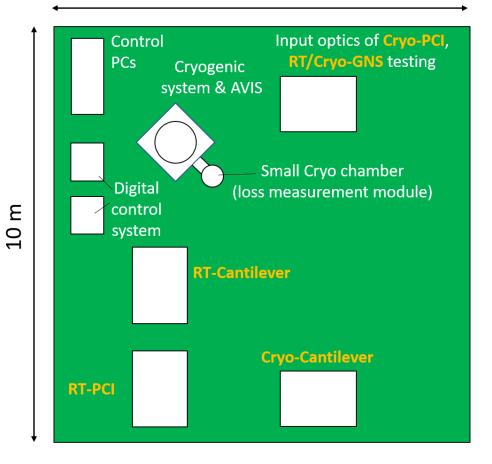


*Fieldbox: pre-processes the signal.





10 m



Mechanical Loss

	Room Temperature (RT)	Cryogenic (~4K)					
3-inches silicon Wafer	 RT-Gentle Nodal Suspension (RT-GNS) 3 NTHU Master's Theses 	Cryo-GNSCooling down					
Cantilever	 RT-Cantilver Moved from NTHU: taking data 	 Cryo-Cantilever Moved from NTHU: under assembly. 					
Optical Loss							
	Room Temperature (RT)	Cryogenic (~4K)					
1-Inch Quartz Substrate	 RT- Photothermal Common path Interferometry (RT-PC Moved from NTHU: under recovery 	• Crvo-PCI					



Summary

- From 2022 to the present, we have been establishing a lab for GW research and the characterization of cryogenic mirror coatings
- NTHU Lab (Prof. Chou retired in 2024) has already moved to ASGRAF
- AVIS for the cryogenic system is developed
- For loss measurement, we have RT/Cryo-[Cantilever, GNS (Mech.), PCI (optical)], 6 machines in total

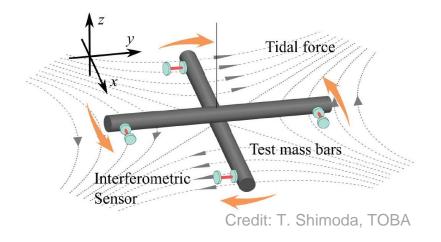
	2024	2024	20	024	2025
	Sep.	Oct.	D	ec.	Mar.
RT-Cantilever	Validation	Run			
Cryo-Cantilever		Move		Run	
RT-GNS	Noise study		Run		
Cryo-GNS		Cooling te	est	Run	
RT-PCI		Move	Assembly	Run	
Cryo-PCI		Input optics	5	cooling test	Run



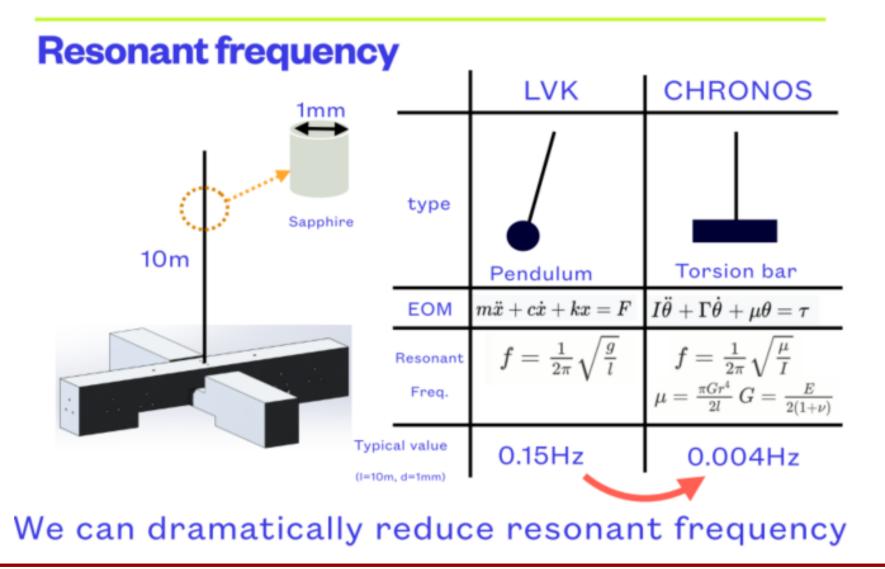


ASGRAF

- Academia Sinica GRAvitational physics research Facility (ASGRAF)
- Laboratory at the basement of ASIoP $(10m \times 10m)$
- Target: Sub-Hz region
- **3** key technologies:
 - □ Two cross bar-shape test masses (torsion bars)
 - → System to be measured
 - □ Speed meter (**sagnac** interferometry)
 - → Measuring apparatus
 - Cryogenic technology

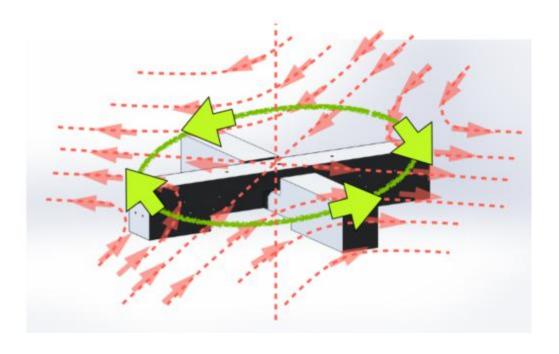


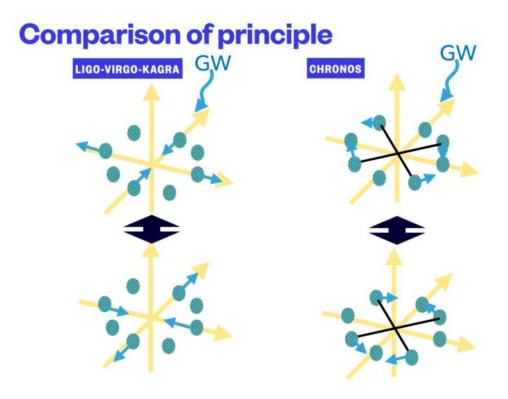






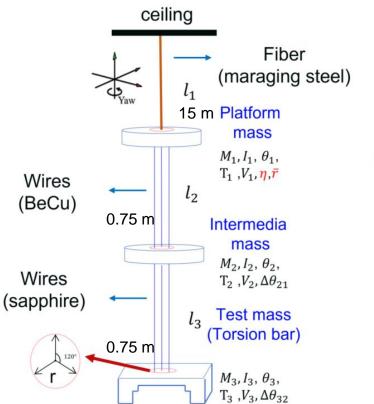
Cross-Torsion Bar





- Metric perturbation (GW) changes the relative angle of cross-bars
- By measuring relative angle, we can reconstruct the gravitational waveform, h(t).

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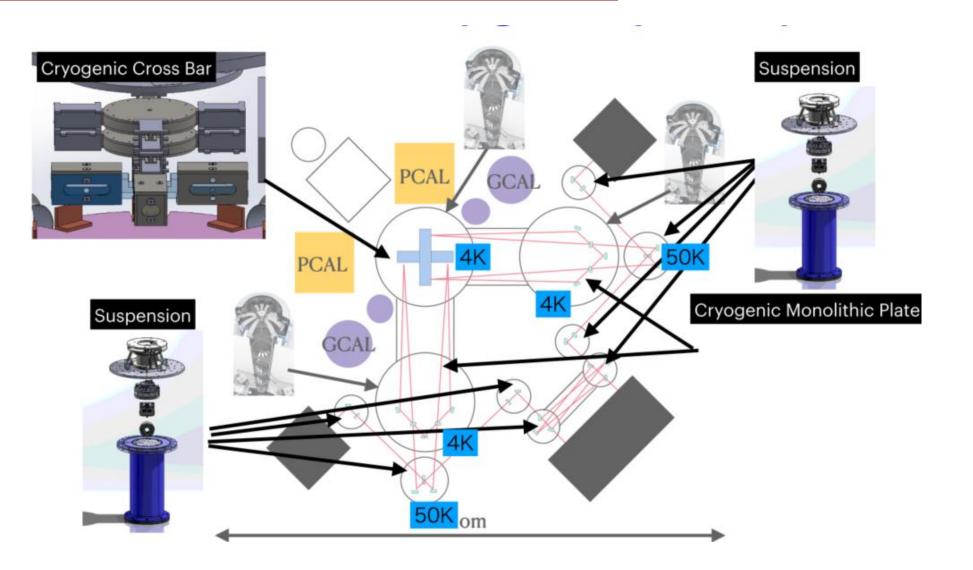


 $\begin{array}{l} M: \text{Mass} \\ I: \text{Moment of inertia} \\ l: \text{length of wires} \\ \theta: \text{Angle of Yaw rotation (w.r.t the ceiling)} \\ T: \text{kinetic energy} \\ V: \text{potential} \\ r: \text{Distance between the center and wires} \\ \overline{r}: \text{radius of Fiber} \\ \eta: \text{Modulus in Torsion (shear modulus)} \\ \Delta \theta_{21}: \theta_2 - \theta_1 \\ \Delta \theta_{32}: \theta_3 - \theta_2 \end{array}$

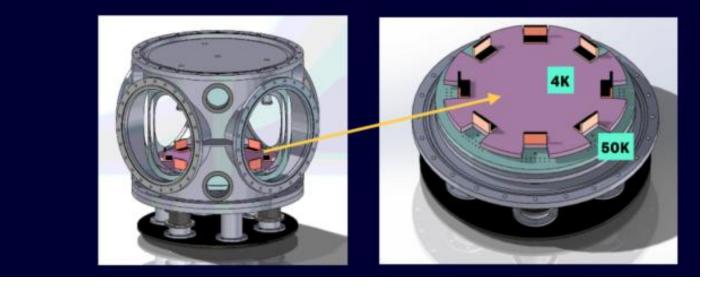
- Resonance Freq. $\Box f_1 = 0.004 \text{ Hz}$
 - $\Box f_2 = 0.107 \text{ Hz}$
 - $\Box f_3 = 0.047 \text{ Hz}$
- We focus on the sub-Hz region
- Bridge LISA (<0.01 Hz) and LIGO (>10 Hz)



Configuration

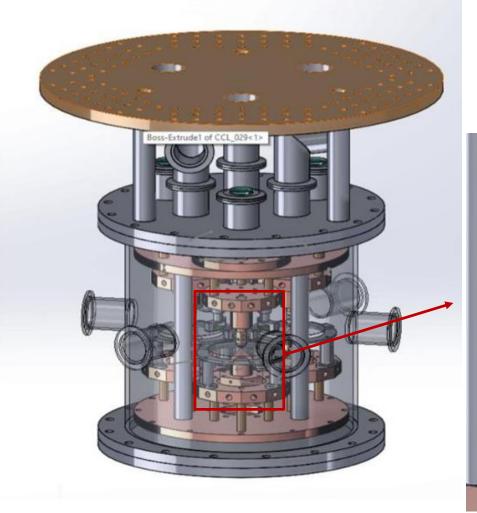


Temperature of large chamber We need to achieve the 4K temperature at main stages. We need to reduce the thermal loading and establish the heatlink technology with pure aluminum wire.

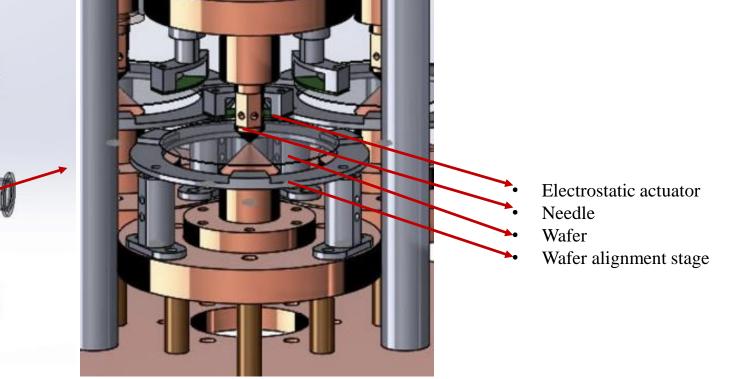




System setup

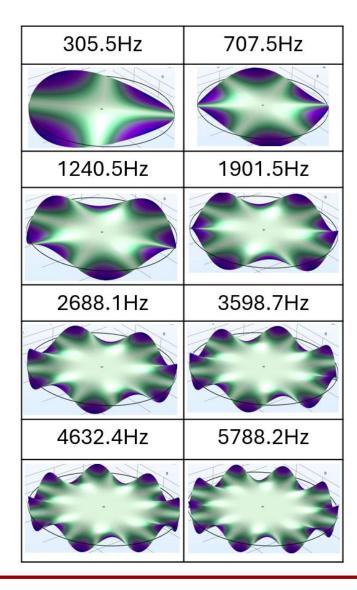


- Design for 3-inch size wafer measurement
- Contains three nodal suspensions, which can perform uncoated wafer measurement, coated wafer measurement, and temperature monitoring at the same time

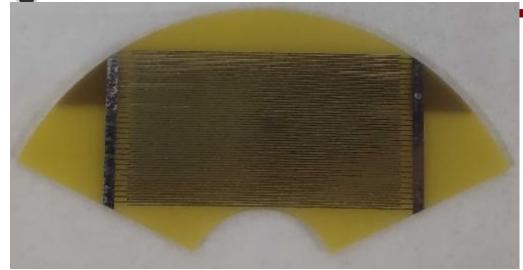


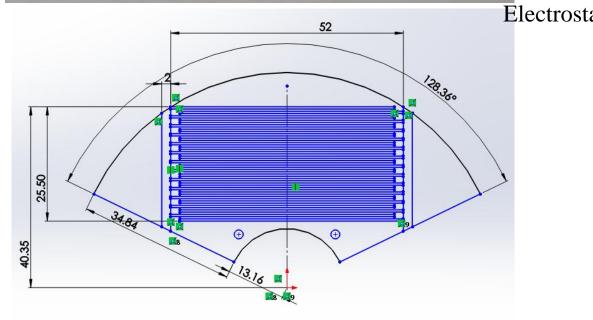


Wafer With 200um thickness









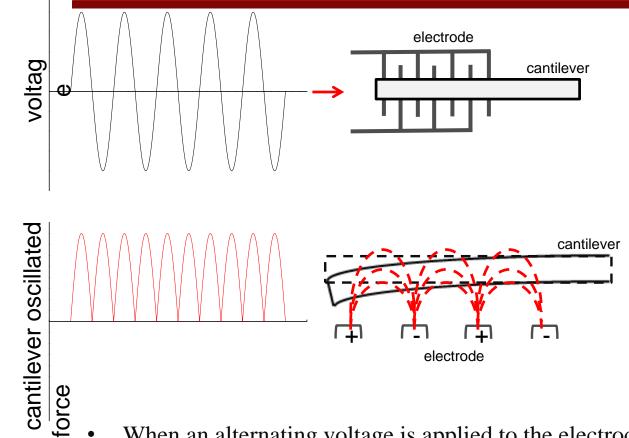
	Dimension of Actuator				
	1.Comb length (Lc)	50mm			
	2. Comb Width (Wc)	0.25mm			
	3. Gap between moving comb and fixed comb (g)	0.1mm			
ati	C 4 .Otura pping area (y0)	48mm			
	5. Thickness of Actuator (t)	30um~35um			
	6. No. of Moving combs (n)	26			

$$C = \frac{2n\varepsilon_0 ty_0}{g}$$
$$= 6.629 \times 10^{-12} (\text{C/V})$$

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Electrostatic actuator



The relation between force, capacitance and electric field is given below.

The relationship between electric field and force: $F = Q \times E$

The relationship between capacitance and charge:

 $Q = C \times V$

The relationship between voltage and electric field: $E = V \div d$

$$\rightarrow F = CV^2/d$$

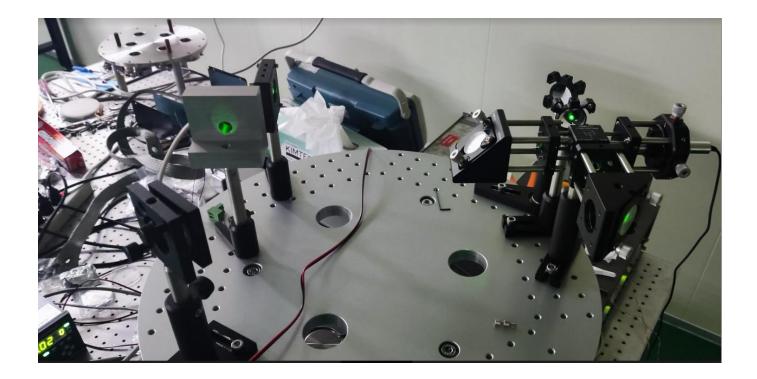
• When an alternating voltage is applied to the electrode plates, an electric field is generated between the electrodes. The cantilever will experience an attractive force due to this electric field, causing it to move towards the electrode plates.

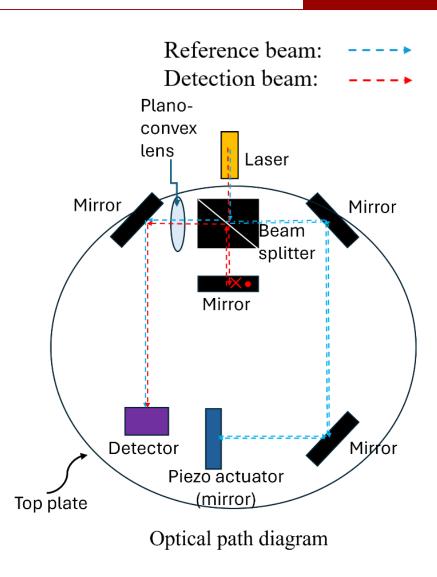
(Dielectric polarization)



Optical measurement system

Use Michelson interferometer to measure the vibration. Use piezo actuator to lock the system. Use convex lens to help us find the interference.

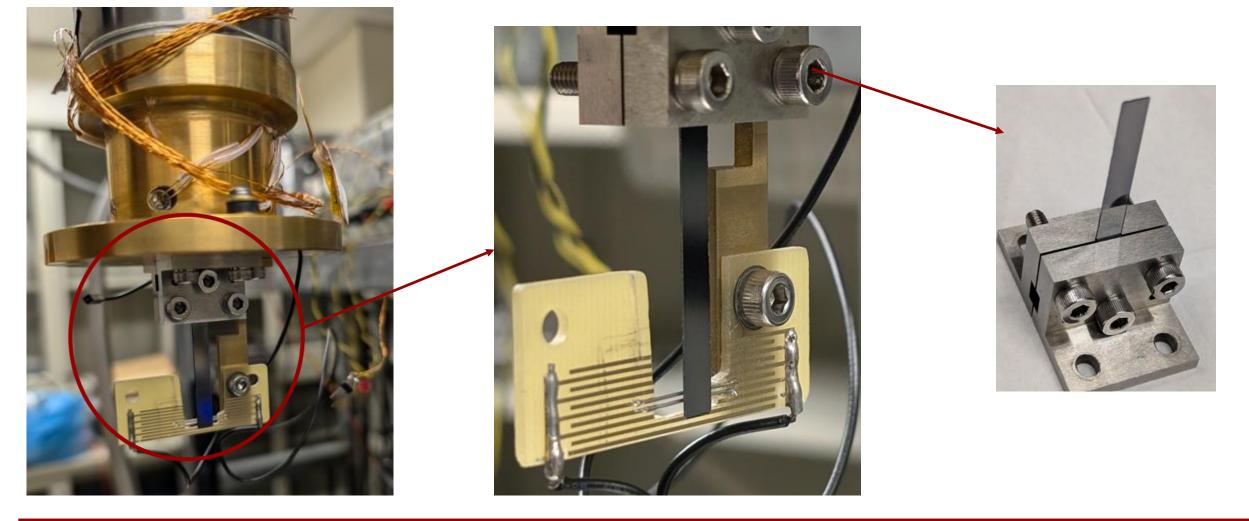






Mechanical Loss (Structural Loss)-2

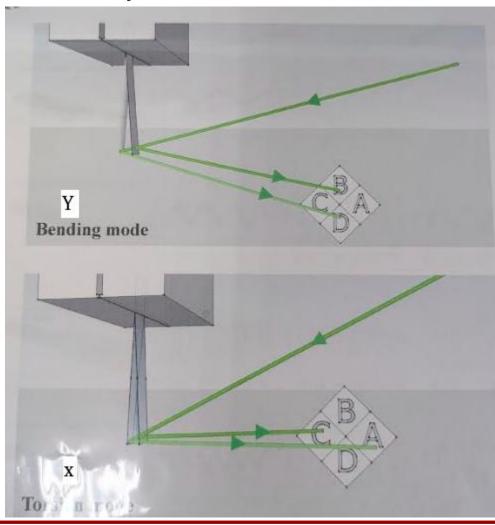
RT/Cryo - Cantilever

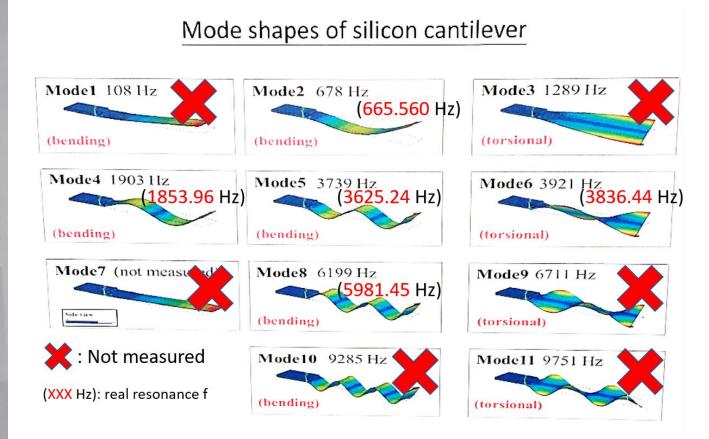




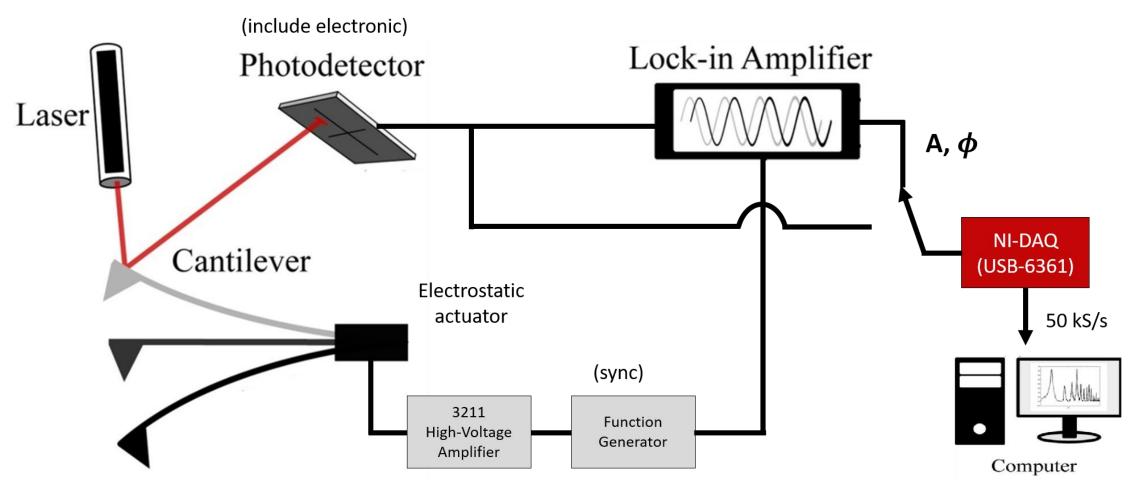
Mechanical Loss (Structural Loss)-2

RT/Cryo - Cantilever





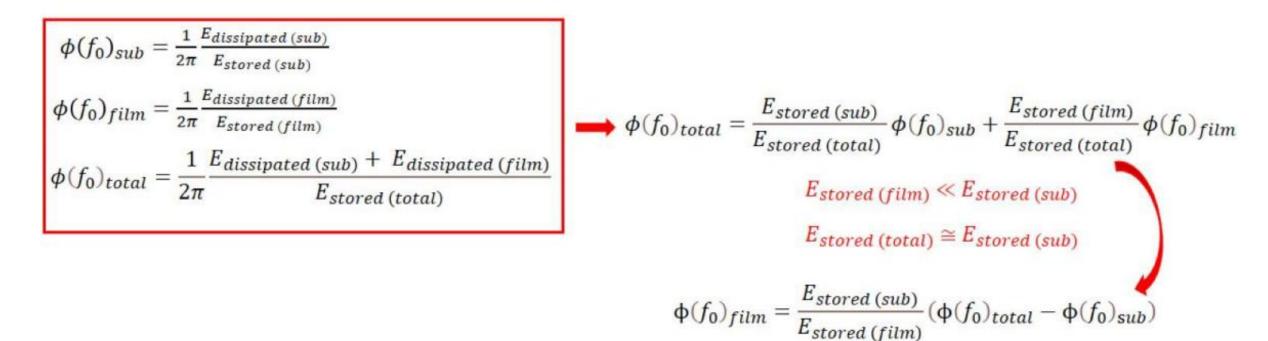
RT/Cryo - Cantilever





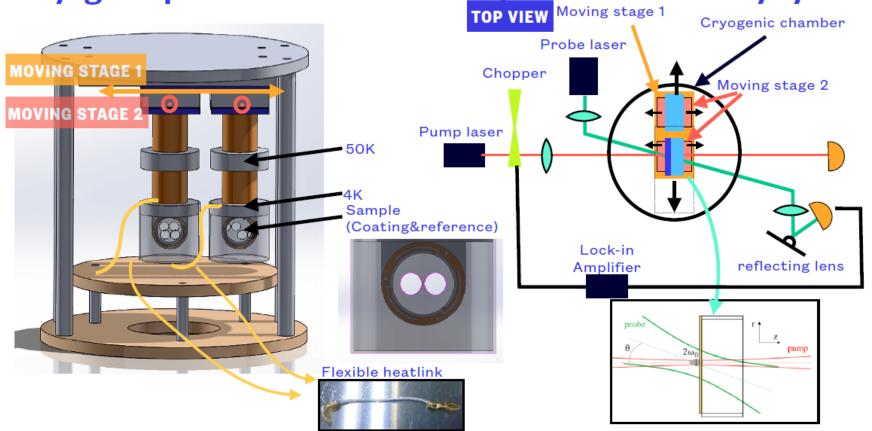
Deriving Q(quality factor) from time constant of ringdown.

$$\phi(f_0) = \frac{1}{Q(f_0)} = \frac{1}{2\pi} \frac{E_{dissipated \ per \ cycle}}{E_{stored}} = \frac{1}{\pi f_0 \tau}$$









Moving stage 1: Replace Coating sample and reference sample

- We will mount the radiation shield around the sample
- We can replace the mirrors with piezo motor.
- Moving stage 2: Alignment of sample position
- We employ the high purity aluminum wire for moving cryogenic stage.

Demodulator

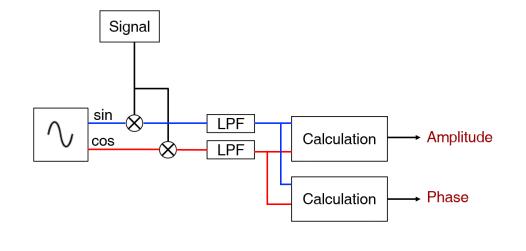
A method to know the **amplitude** and **phase** of signal at a certain frequency in real-time

Signal to be measured:

 $s(t) = A(t) \sin(\omega t + \phi)$ + other frequency component 1.Oscillator

$$\begin{split} s(t) \cdot \sin(\omega' t) &= A(t) \cdot \sin(\omega t + \phi) \cdot \sin(\omega' t) \\ &= \frac{1}{2} A(t) \cos((\omega t + \phi) + \omega' t) - \frac{1}{2} A(t) \cos((\omega t + \phi) - \omega' t). \\ s(t) \cdot \cos(\omega' t) &= A(t) \cdot \sin(\omega t + \phi) \cdot \cos(\omega' t) \\ &= \frac{1}{2} A(t) \sin((\omega t + \phi) + \omega' t) + \frac{1}{2} A(t) \sin((\omega t + \phi) - \omega' t) \\ \mathbf{2.Apply Low-Pass Filter} \\ \mathrm{LPF}\{s(t) \cdot \sin(\omega' t)\} &= -\frac{1}{2} A(t) \cos((\omega t + \phi) - \omega' t). \\ \mathrm{LPF}\{s(t) \cdot \cos(\omega' t)\} &= \frac{1}{2} A(t) \sin((\omega t + \phi) - \omega' t). \end{split}$$

 $(\omega - \omega')$ should be close to 0 for discarding other frequency components



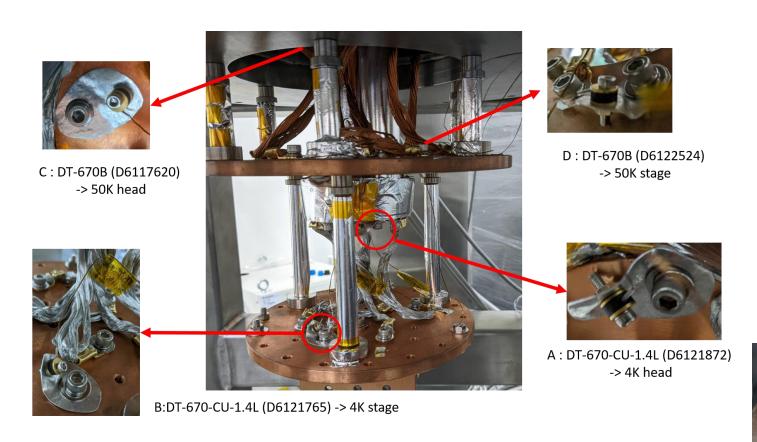
Amplitude

 $A(t) = 2\sqrt{\left(\mathrm{LPF}\{s(t) \cdot \sin\left(\omega't\right)\}\right)^2 + \left(\mathrm{LPF}\{s(t) \cdot \cos\left(\omega't\right)\}\right)^2}$

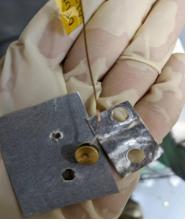
Phase $((\omega t + \phi) - \omega' t) = \tan^{-1} \left(-\frac{\operatorname{LPF}\{s(t) \cdot \cos(\omega' t)\}}{\operatorname{LPF}\{s(t) \cdot \sin(\omega' t)\}}\right).$



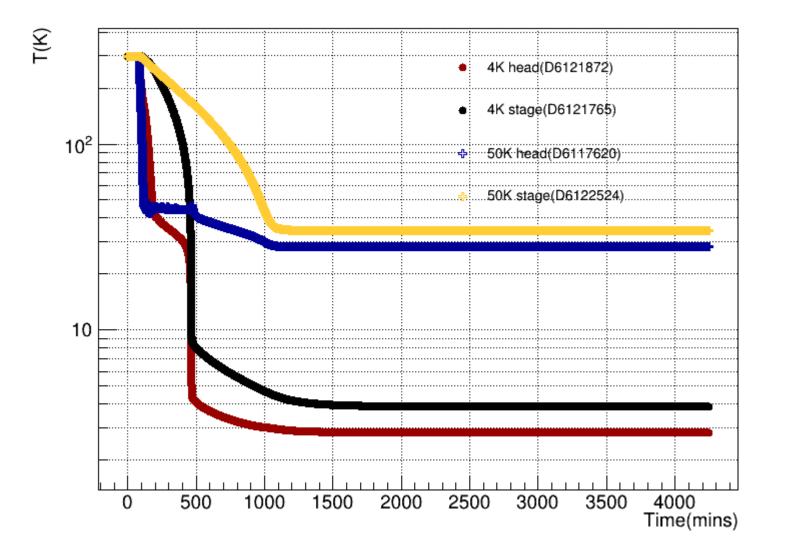
Thermometers installation



Sensor: Can be mounted to any flat surface with a 4-40 or M3 screw







- ~ 25 hours
 - **Final Temperature**
- Upper part: □ Head: 27.9 K

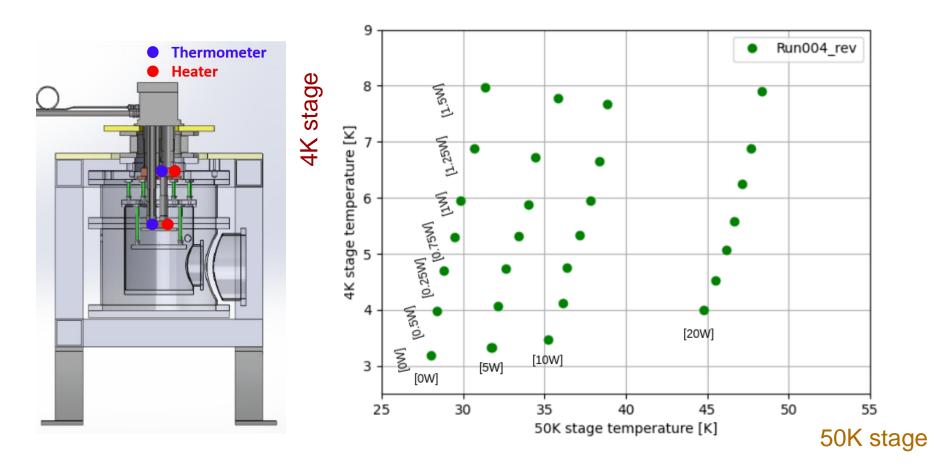
□ Stage: 34.16 K

- Lower part:
 - □ Head: 2.80 K
 - □ Stage: 3.87 K

NSGRAF

Working field of cryogenics

To validate that the target temperatures will be reached, it is crucial to have a load map ("working field") of the used cryocooler.

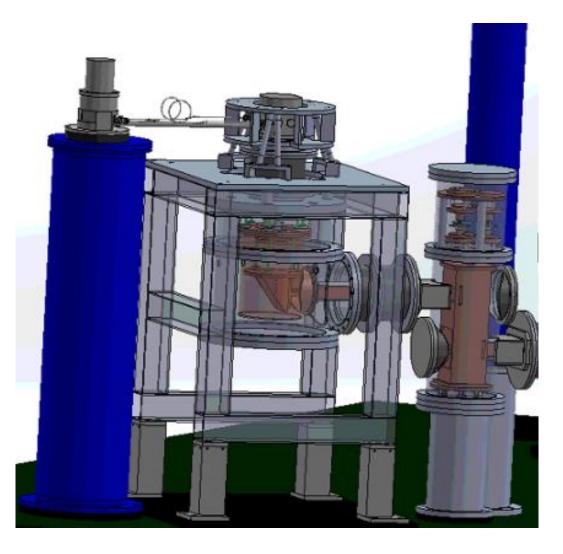


2023 TPS meeting

ASGRAF



Cryogenic design



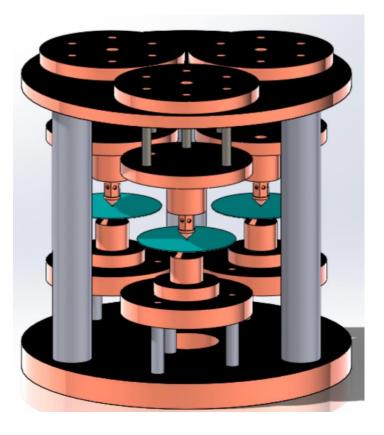
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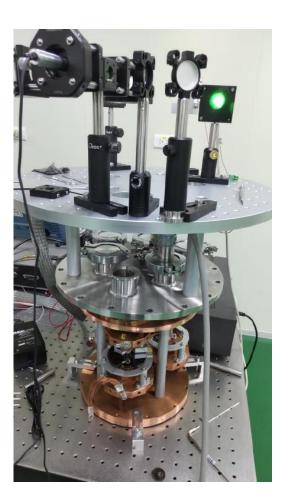


Mechanical Loss (Structural Loss)-1

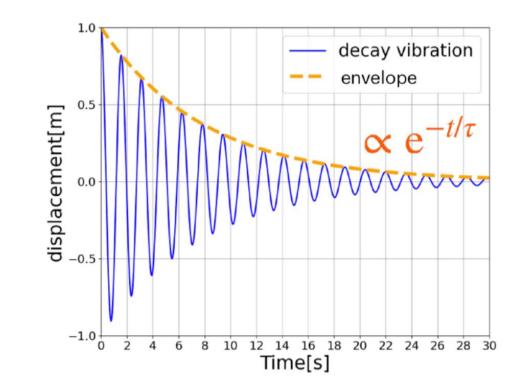
RT/Cryo - Gentle Nodal Suspension (GNS)

[Newly developed system]





- Excite modes with an electrostatic actuator
- Measure vibration with a Michelson interferometer.

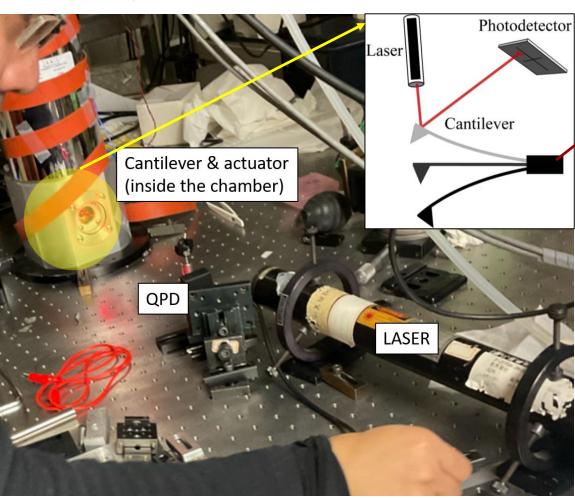


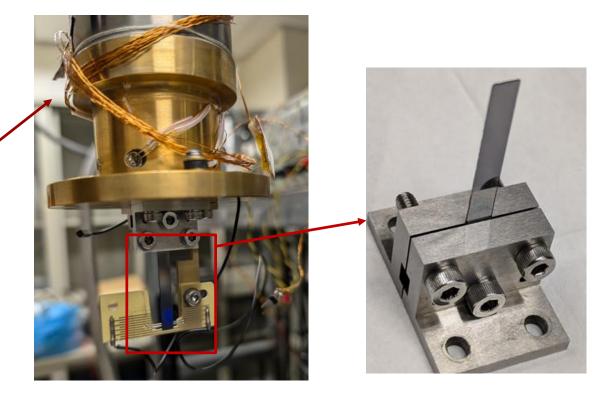


Mechanical Loss (Structural Loss)-2

RT/Cryo - Cantilever [Legac

[Legacy system from NTHU]

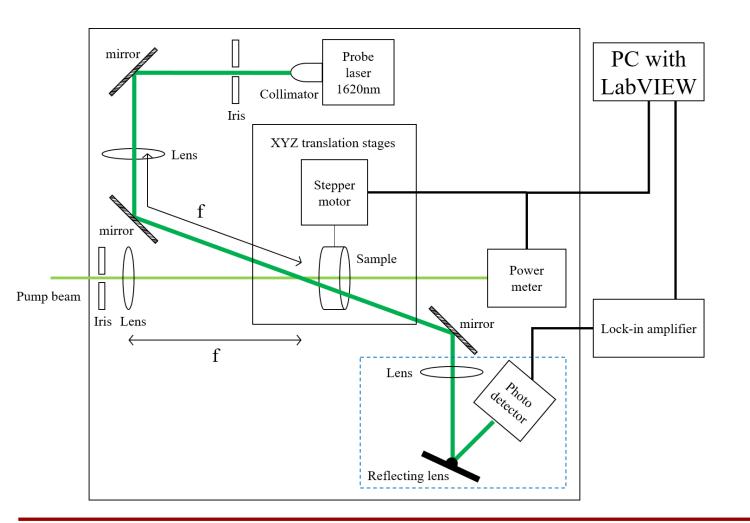




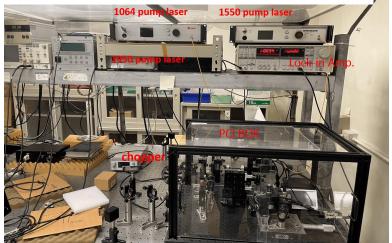
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Optical Loss (Absorption-related Thermal Noise)

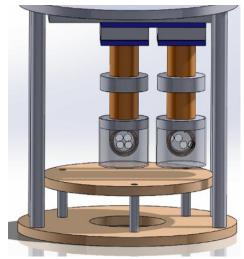
RT/Cryo-Photothermal Common-path Interferometry (PCI)



[RT: Legacy system from NTHU] 🚪



[Cryo: Newly developed system]



ASGRAF



Cryogenic system & AVIS

