2024 CHiP Annual Meeting

The New AS GW Laboratory – Status and Plans

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> Prof. Henry Tsz-King Wong, Prof. Yuki Inoue, Prof. Shiuh Chao ASGRAF team 2024/11/20

The New AS GW Laboratory

- **^A**cademia **^S**inica **GRA**vitational research **^F**acility (**ASGRAF**)
- IOP B1 10×10 m^2 , Clean Room Spec @ C-10000
- Menu (plan) ❑ GW "System" Test Facility ❑ Cryo & Mirror & AVIS Research ❑ Move NTHU Lab ❑ Future CHRONOS prototype

Group member

- Collaboration team: AS + NCU + NTHU
- Prof. Chao retired after Jul. 2024 ❑ Move to ASGRAF
- A new gas line was built for LPCVD SiON fabrication in TSRI (Kun-Yao Chang's report).

- **Henry Tsz-King Wong**
- Feng-Kai Lin
- Daiki Tanabe
- Hsiang-Chieh Hsu
- Vivek Kumar

• **Yuki Inoue** • Avani Patel

• You-Ru Lee

• Yi-Shong Lin

• Dennis Yu

• Yoyo Huang

• Hsiang-yu huang • Miftahul Ma'arif

• Cheng-Han Chan • Kun-Yao Chang

NCU NTHU

- **Shiuh Chao 趙煦 (Retired)**
- Chien-Yu Lin (Grad.)
- Chun-Huan Wang (Grad.)
- Dong-Yu Chen (Grad.)
- Zi-Yu Wang (Grad.)


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AS

Construction: Lab design schematic ⁴

NSGRAF

TIMELINE

2022/09: Clean old Lab **2023/01: construction 2023/03: clean room finish & testing**

2024/05: moving instrument into Lab 2024/10: moving NTHU Lab

Status now

Before (Sep. 2022) Now (Nov. 2024)

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■ Loss measurement: 3 Machine (**Cantilever, GNS, PCI**) * 2 version (RT/Cryo): 6 in total

(**GNS**: **G**entle **N**oodle **S**uspension; **PCI**: **P**hotothermal **C**ommon-path **I**nterferometry)

■ **Active Vibration Isolation System (AVIS)**

: Newly developed system : Legacy system from NTHU

- Many sensors and actuators: **C**ontrol and **D**ata **S**ystem (**CDS**) by LIGO
- **Hardware**: To form multiple-input multiple-output control loops
- ❑ DAC, ADC
- ❑ PCIe extension board, I/O board and timing board connecting with Standalone system
- ❑ AA and AI filters
- **Software**: based on a real-time enabled Linux operating system
- ❑ **E**xperimental **P**hysics and **I**ndustrial **C**ontrol **S**ystem (**EPICS**): operators control screens and channel access
- ❑ Matlab/Simulink tools: workflow for a digital control circuit.
- ❑ Creating a real-time kernel module from this circuit model by Matlab/Simulink, and control the module via EPICS

*Fieldbox: pre-processes the signal.

\blacksquare 3 Machine $*$ 2 version $+$ 1: 7 in total

 10_m

Mechanical Loss

Summary

- From 2022 to the present, we have been establishing a lab for GW research and the characterization of cryogenic mirror coatings
- NTHU Lab (Prof. Chou retired in 2024) has already moved to ASGRAF
- AVIS for the cryogenic system is developed
- For loss measurement, we have RT/Cryo-[Cantilever, GNS (Mech.), PCI (optical)], 6 machines in total

ASGRAF

- **^A**cademia **^S**inica **GRA**vitational physics research **^F**acility (**ASGRAF**)
- Laboratory at the basement of ASIoP $(10m \times 10m)$
- Target: **Sub-Hz region**
- **³** key **technologies**:
	- ❑ Two **cross bar-shape** test masses (torsion bars)
		- **System** to be **measured**
	- ❑ Speed meter (**sagnac** interferometry)
	- **Measuring apparatus**
	- ❑ **Cryogenic** technology

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Cross-Torsion Bar

- Metric perturbation (GW) changes the relative angle of cross-bars
- \blacksquare By measuring relative angle, we can reconstruct the gravitational waveform, h(t).

 $M:$ Mass *I* : Moment of inertia l : length of wires θ : Angle of Yaw rotation (w.r.t the ceiling) T: kinetic energy V : potential r: Distance between the center and wires \bar{r} : radius of Fiber η : Modulus in Torsion (shear modulus) $\Delta\theta_{21}$: $\theta_2 - \theta_1$ $\Delta\theta_{32}$: $\theta_3 - \theta_2$

- **Resonance Freq.**
	- $\Box f_1 = 0.004 \text{ Hz}$
	- $\Box f_2 = 0.107$ Hz
	- $\Box f_3 = 0.047$ Hz
- \blacksquare We focus on the sub-Hz region

❑ Bridge LISA (<0.01 Hz) and LIGO (>10 Hz)

Configuration

Temperature of large chamber We need to achieve the 4K temperature at main stages. We need to reduce the thermal loading and establish the heatlink technology with pure aluminum wire.

System setup

- Design for 3-inch size wafer measurement
- Contains three nodal suspensions, which can perform uncoated wafer measurement, coated wafer measurement, and temperature monitoring at the same time

Wafer With 200um thickness

$$
C = \frac{2n\varepsilon_0 t y_0}{g}
$$

= 6.629 × 10⁻¹²(C/V)

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Electrostatic actuator

The relation between force, capacitance and electric field is given below.

The relationship between electric field and force: $F = Q \times E$

The relationship between capacitance and charge:

 $Q = C \times V$

The relationship between voltage and electric field: $E = V \div d$

$$
\rightarrow F = CV^2/d
$$

When an alternating voltage is applied to the electrode plates, an electric field is generated between the electrodes. The cantilever will experience an attractive force due to this electric field, causing it to move towards the electrode plates.

(Dielectric polarization)

Optical measurement system

Use Michelson interferometer to measure the vibration. Use piezo actuator to lock the system. Use convex lens to help us find the interference.

Mechanical Loss (Structural Loss)-2

▪ RT/Cryo - **Cantilever**

Mechanical Loss (Structural Loss)-2

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▪ RT/Cryo - **Cantilever**

Deriving Q(quality factor) from time constant of
ringdown.

$$
\phi(f_0) = \frac{1}{Q(f_0)} = \frac{1}{2\pi} \frac{E_{dissipated\ per\ cycle}}{E_{stored}} = \frac{1}{\pi f_0 \tau}
$$

Moving stage 1: Replace Coating sample and reference sample

- . We will mount the radiation shield around the sample
- . We can replace the mirrors with piezo motor.
- Moving stage 2: Alignment of sample position
- . We employ the high purity aluminum wire for moving cryogenic stage.

Demodulator

■ A method to **know** the **amplitude** and **phase** of signal at a certain frequency in real-time

Signal to be measured:

 $s(t) = A(t) \sin(\omega t + \phi) +$ other frequency component 1.Oscillator

$$
s(t) \cdot \sin(\omega' t) = A(t) \cdot \sin(\omega t + \phi) \cdot \sin(\omega' t)
$$

\n
$$
= \frac{1}{2}A(t) \cos((\omega t + \phi) + \omega' t) - \frac{1}{2}A(t) \cos((\omega t + \phi) - \omega' t).
$$

\n
$$
s(t) \cdot \cos(\omega' t) = A(t) \cdot \sin(\omega t + \phi) \cdot \cos(\omega' t)
$$

\n
$$
= \frac{1}{2}A(t) \sin((\omega t + \phi) + \omega' t) + \frac{1}{2}A(t) \sin((\omega t + \phi) - \omega' t)
$$

\n2.Apply Low-Pass Filter
\nLPF{ $s(t) \cdot \sin(\omega' t)$ } = $-\frac{1}{2}A(t) \cos((\omega t + \phi) - \omega' t)$
\nLPF{ $s(t) \cdot \cos(\omega' t)$ } = $\frac{1}{2}A(t) \sin((\omega t + \phi) - \omega' t)$.

 $(\omega - \omega')$ should be **close to 0** for discarding other frequency components

Amplitude

 $A(t) = 2\sqrt{\left(\text{LPF}\{s(t)\cdot\sin{(\omega' t)}\}\right)^2 + \left(\text{LPF}\{s(t)\cdot\cos{(\omega' t)}\}\right)^2}$

Phase
 $(\omega t + \phi) - \omega' t) = \tan^{-1} \left(-\frac{\text{LPF}\lbrace s(t) \cdot \cos(\omega' t) \rbrace}{\text{LPF}\lbrace s(t) \cdot \sin(\omega' t) \rbrace} \right).$

Thermometers installation

Sensor: Can be mounted to any flat surface with a 4-40 or M3 screw

- \blacksquare ~ 25 hours
	- Final Temperature
- Upper part: ❑Head: 27.9 K
- ❑Stage: 34.16 K
- **Lower part:** ❑ Head: 2.80 K
	- ❑ Stage: 3.87 K

ASGRAF

Working field of cryogenics

■ To validate that the target temperatures will be reached, it is crucial to have a load map ("working field") of the used cryocooler.

2023 TPS meeting
 ASGRAF

Cryogenic design

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Mechanical Loss (Structural Loss)-1

■ RT/Cryo - Gentle Nodal Suspension (GNS)

[Newly developed system]

- Excite modes with an electrostatic actuator
- Measure vibration with a Michelson interferometer.

Mechanical Loss (Structural Loss)-2

[Legacy system from NTHU]

Optical Loss (Absorption-related Thermal Noise)

▪RT/Cryo-**P**hotothermal **^C**ommon-path **^I**nterferometry (**PCI**)

[RT: Legacy system from NTHU]

[Cryo: Newly developed system]

ASGRAF

Cryogenic system & AVIS

