

Study of KAGRA noise contribution in O3GK

Status of Noise Budget Paper

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on behalf of the KAGRA collaboration

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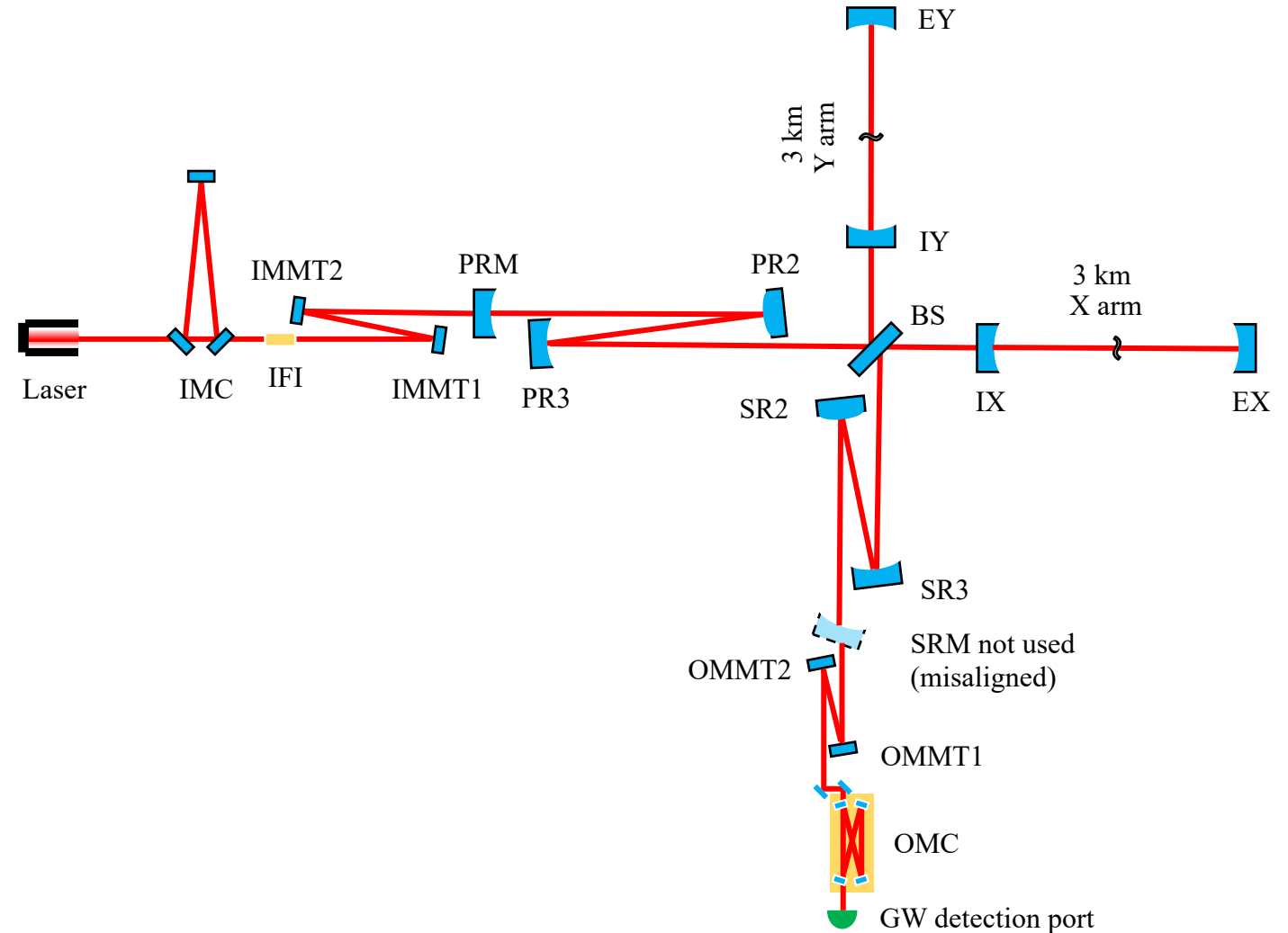
JGW-G2012315

Introduction

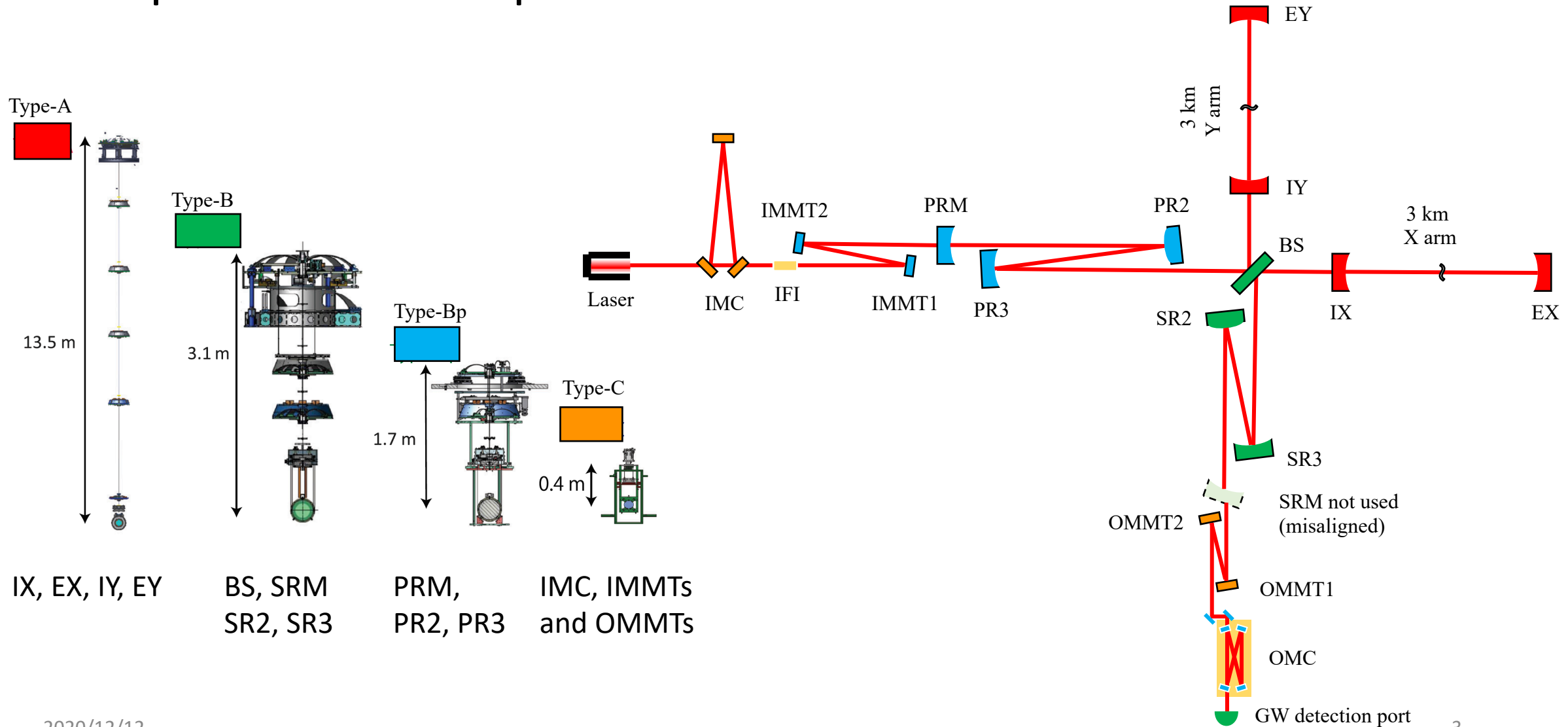
- KAGRA and GEO600 (Hannover, Germany) were operated for observation in April 2020 (O3GK), just after LIGO and Virgo were shut down because of COVID-19.
- In improvement for O4, it is crucial to investigate what kinds of noise dominated sensitivity in O3GK (and we intend to publish).
- We are collecting and summarizing pieces of information.
- We report latest update.

Interferometer Configuration during O3GK

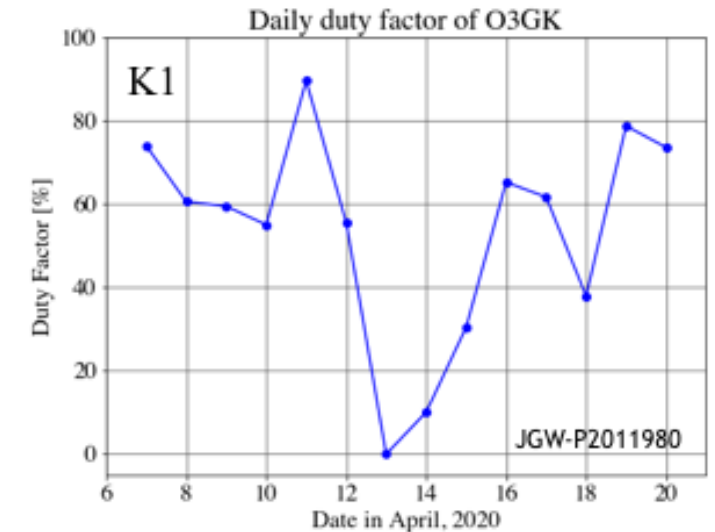
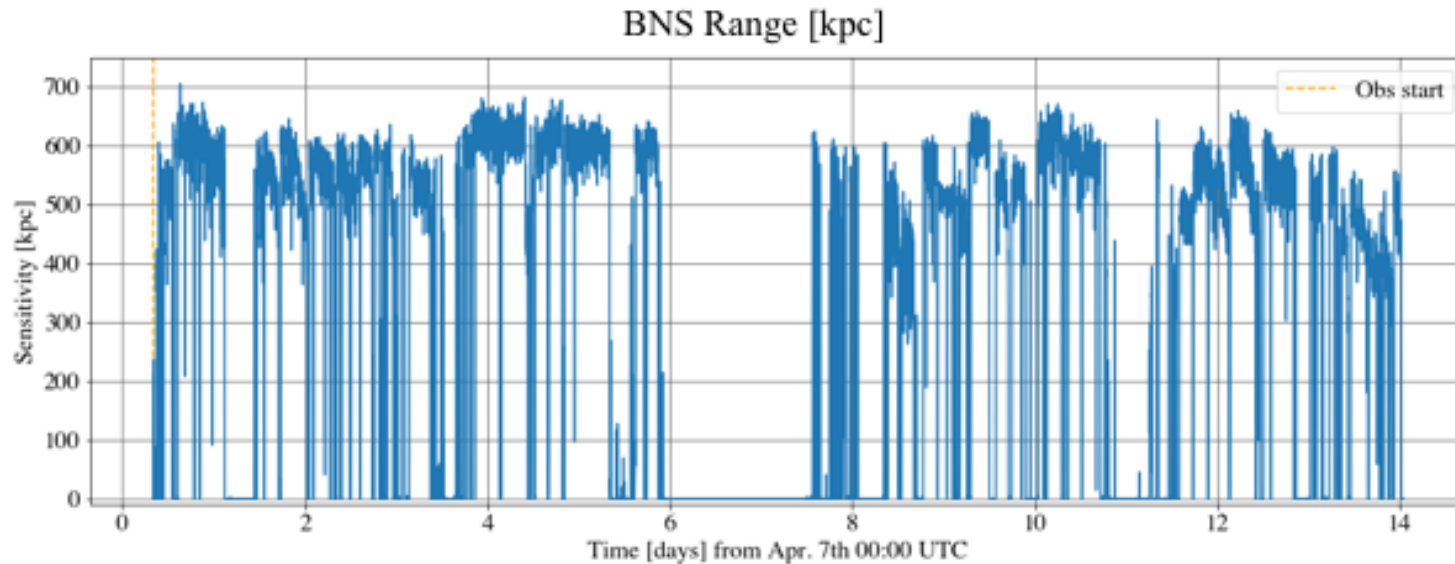
- Power-Recycled Fabry-Perot Michelson interferometer
- 4 DoFs to length-control
 - **CARM** - Common arm length
 - **DARM** - Differential arm length which is GW DoF
 - **PRCL** - Power Recycling Cavity
 - **MICH** - Short differential Michelson ifo



Suspension Map for the KAGRA interferometer



Interferometer status during O3GK



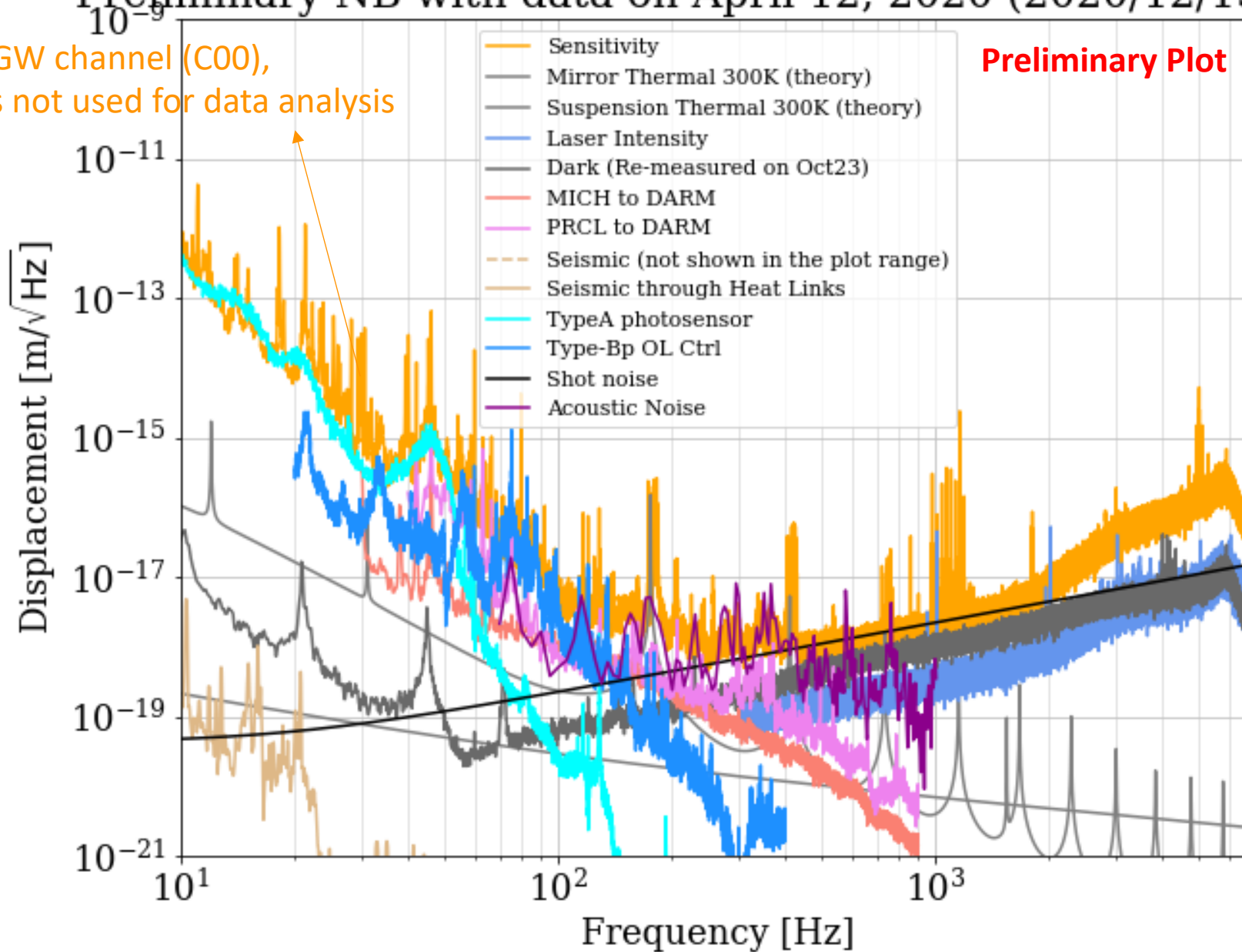
- Typical Binary Neutron Star Range is 600kpc.
- Short lock duration degrades the duty factor.
- More than one day of down time due to high ocean waves due to a bad weather (See, Fujikawa's presentation, abstract ID 16 for detailed study)

	Observation Time [s]	Duty Factor
GEO	940133 (11 days)	80%
KAGRA	628135 (7.3 days)	53%
Coincident	551340 (6.4 days)	47%

from Tagoshi-san material [?]

Preliminary NB with data on April 12, 2020 (2020/12/15 ver)

Online GW channel (C00),
which is not used for data analysis



- Suspension Thermal
 - Theoretical at 300K
Formulae in “Overview of KAGRA: Detector design and construction history” [1]

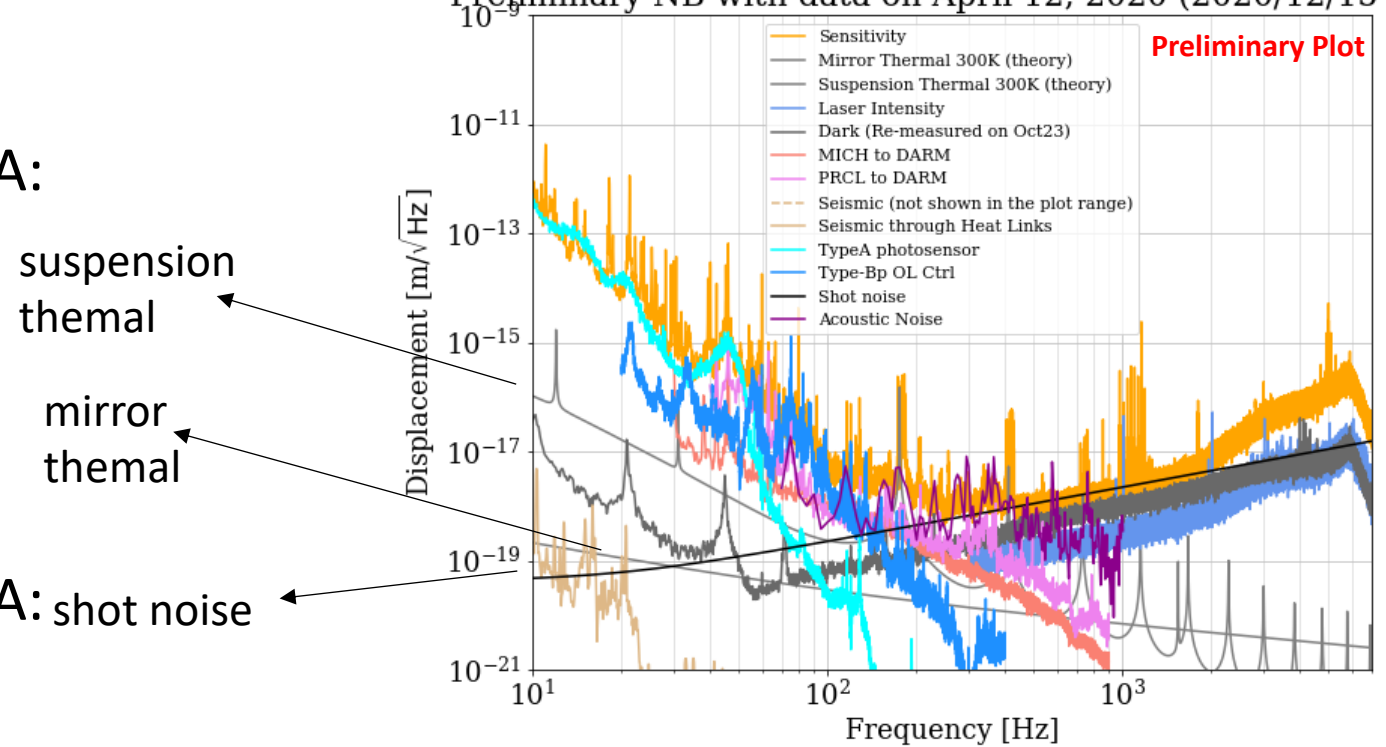
- Mirror Thermal
 - Theoretical at 300K
Formulae in “Overview of KAGRA: Detector design and construction history” [2]

- Shot noise
 - Theoretical formula :

$$G_{\text{shot}} = \frac{h\lambda c}{32G_p I(1-\eta)L^2\mathcal{F}^2} \left[1 + \left(\frac{f}{f_{\text{cut}}} \right)^2 \right],$$

$$f_{\text{cut}} = \frac{c}{4L\mathcal{F}}.$$

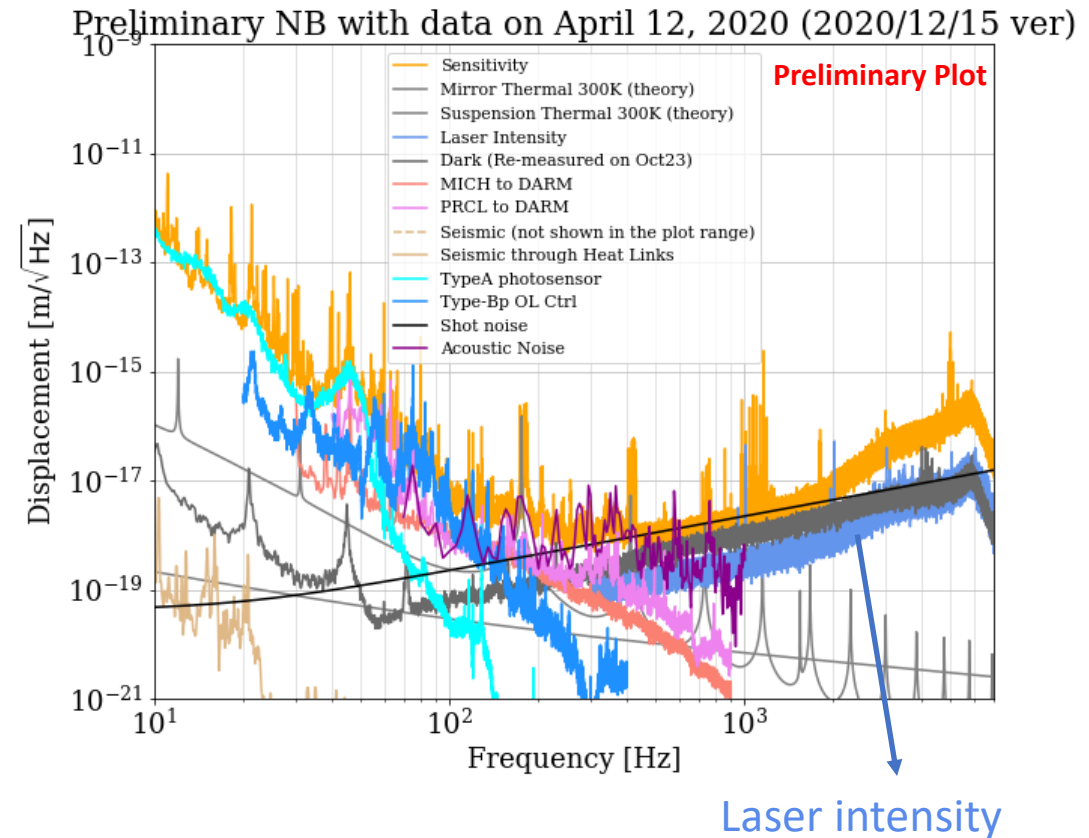
Preliminary NB with data on April 12, 2020 (2020/12/15 ver)



[1] <https://academic.oup.com/ptep/advance-article/doi/10.1093/ptep/ptaa125/5893487>
 [2] <https://academic.oup.com/ptep/advance-article/doi/10.1093/ptep/ptaa125/5893487>

• Laser Intensity

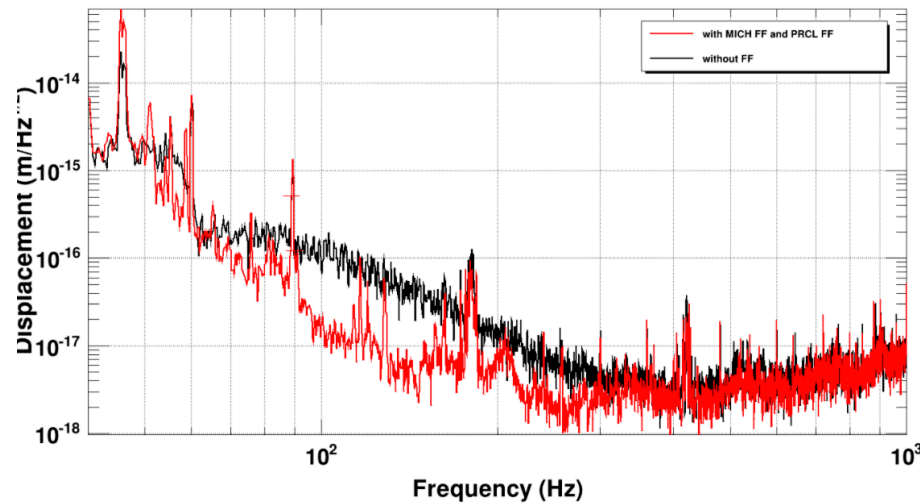
- Laser intensity is stabilized
- Fluctuation of laser power transmitted by IMMT1 was monitored to adjust injected power to interferometer.
- Transfer function from power transmitted by IMMT1 to DARM (gravitational wave signal port) was measured.
- Noise contribution is the product of above fluctuation and transfer function.
- It is not limiting the sensitivity for O3GK, however, it will in O4. Intensity stabilization system is being upgraded (placing PDs in vacuum). [See Kuromiya-kun's presentation, abstract ID 38](#)



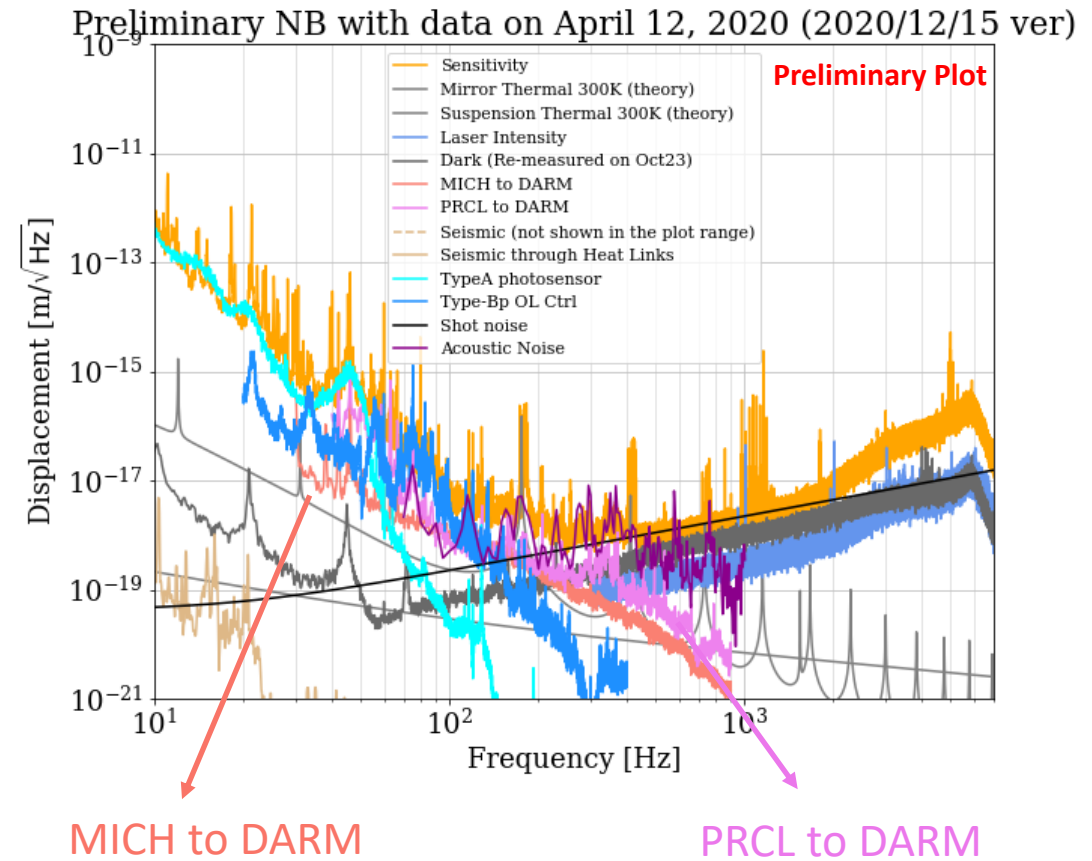
- **MICH** and **PRCL** to DARM coupling

- MICH and PRCL feedforward (FF) loops are improving the sensitivity at 70-200 Hz

- MICH to PRCL FF
 - MICH to DARM FF
 - PRCL to DARM FF

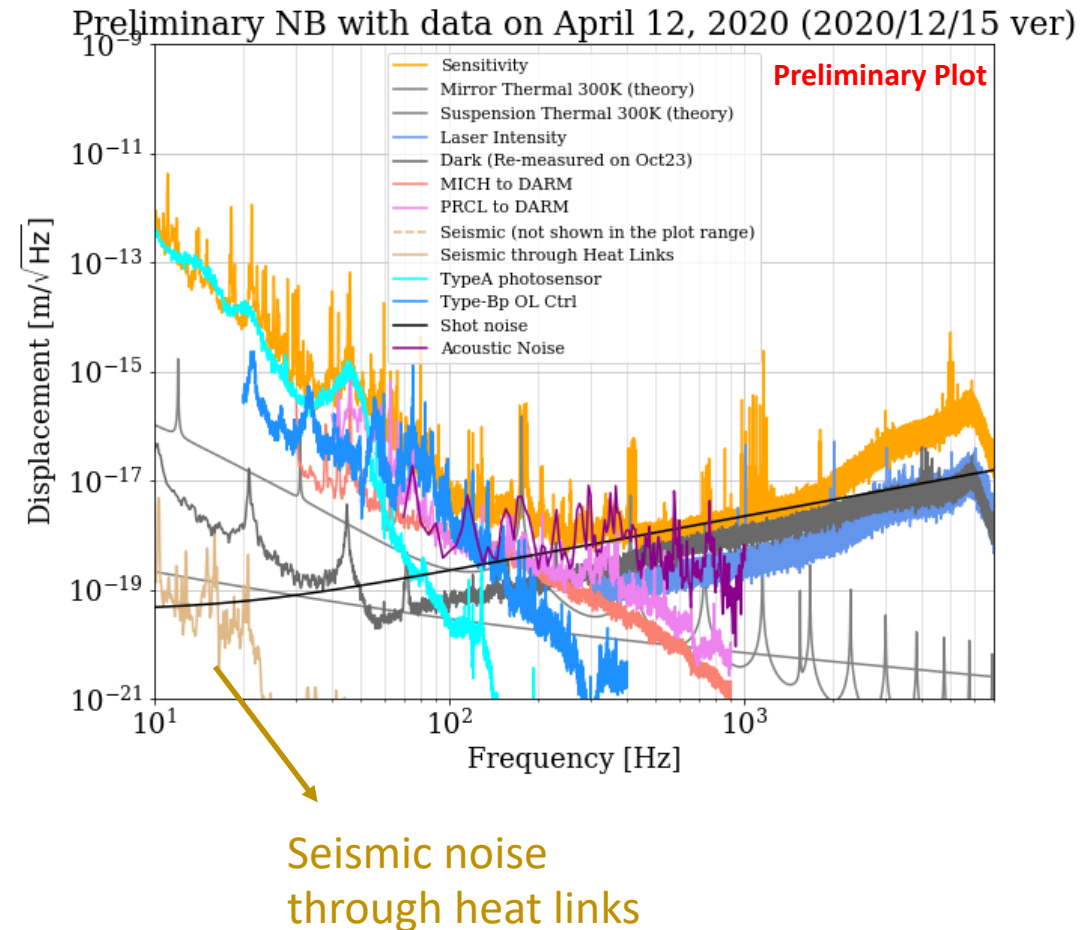


- Residual contribution was estimated
 - More tuning (e.g., FF gain, diagonalization) is necessary for O4



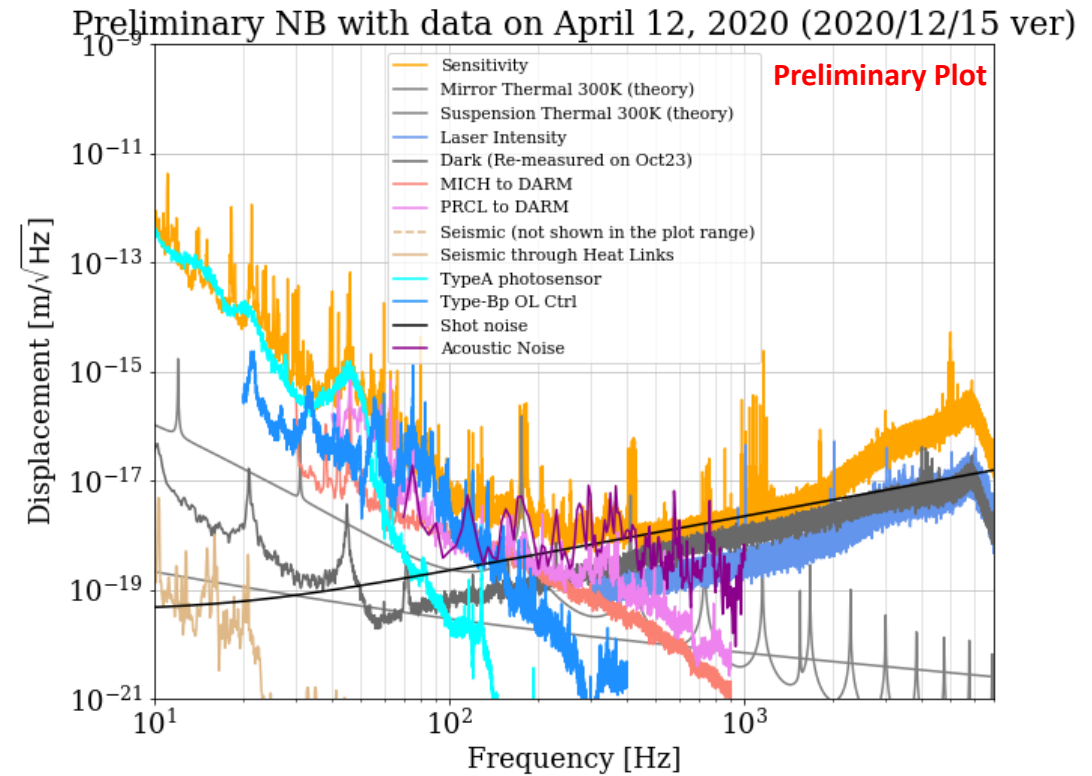
• Seismic Noise through Heat Links

- There are heat links made from pure aluminum as heat path to cool down sapphire mirrors. They can transfer vibration to sapphire mirror.
- Low and not contributing to DARM
- The modeled transfer function from the suspension point of the heat link vibration isolation system to the test mass was evaluated by Shoda-san.
- Suspension point vibration is assumed to be same as vibration at a floor of inner radiation shield (measured by Ochi-kun [1]).
- Updated study by Yamada-kun's Ph.D. thesis (presentation at KIW - abstract ID 64)



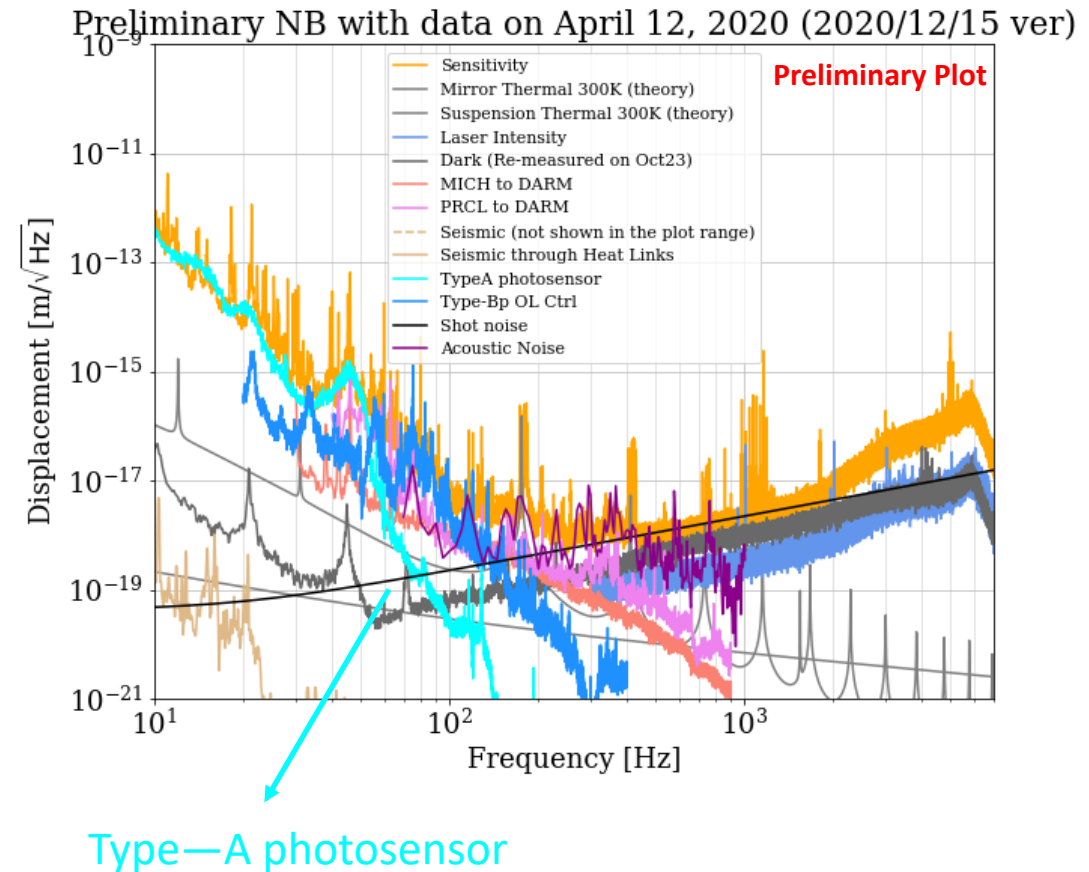
[1] <https://gwdoc.icrr.u-tokyo.ac.jp/cgi-bin/DocDB/ShowDocument?docid=7574>

- Seismic Noise thorough type-A suspension
 - Enough low and not appear in this plot
 - Estimated by the modeled transfer function from Type-A ground to test mass (by Shoda-san) x seismometer data

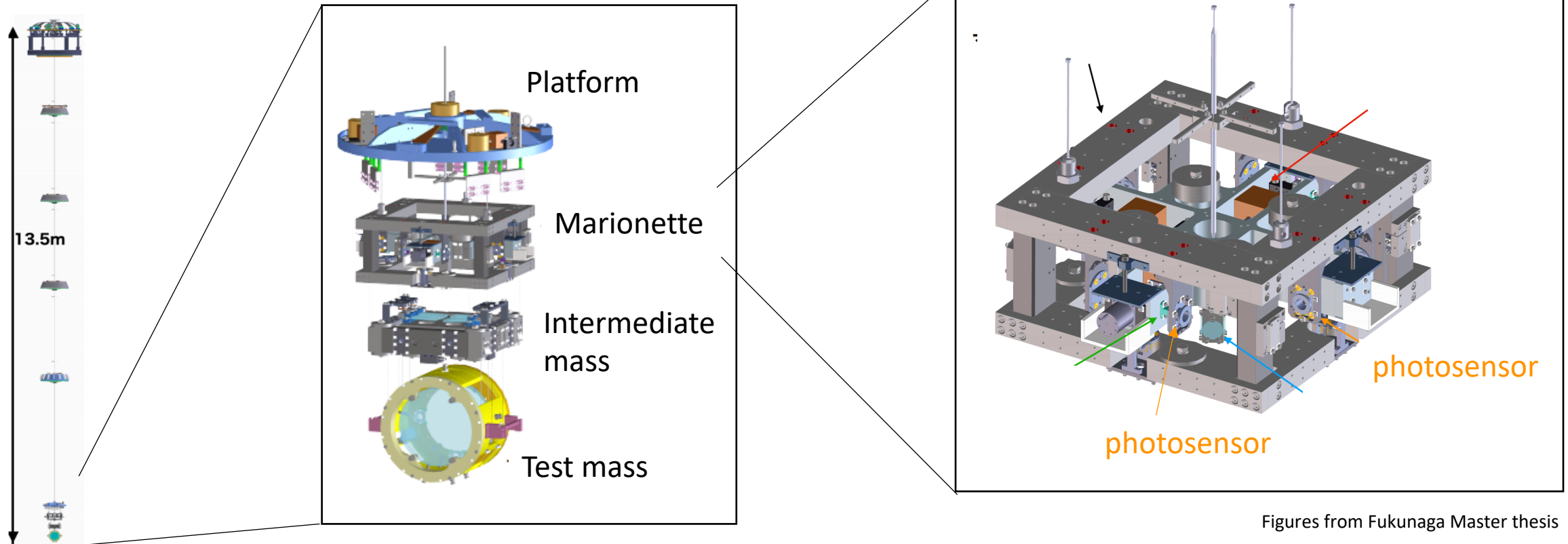


- Type—A photosensor

- Photosensors are used for local damping of Type-A suspensions (four mirrors in the arms) to suppress resonant motion of suspensions.
- Transfer function from Marionetta (MN) photosensor to DARM was measured (klog 13470 and its thread).
- Contribution to DARM is estimated by the online witness channel for MN photo sensor on Apr 12 multiplied by the transfer function
- IX photosensor is most noisy of the four and limits the sensitivity
- Planning to substitute with optical levers, under investigation

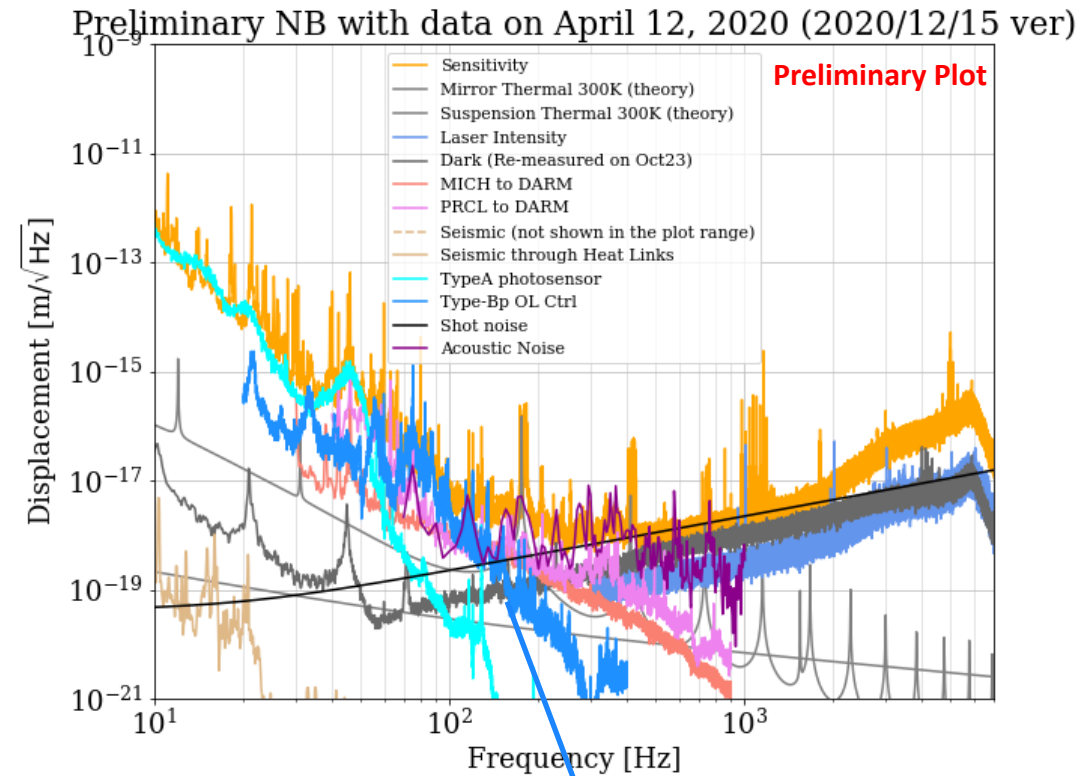


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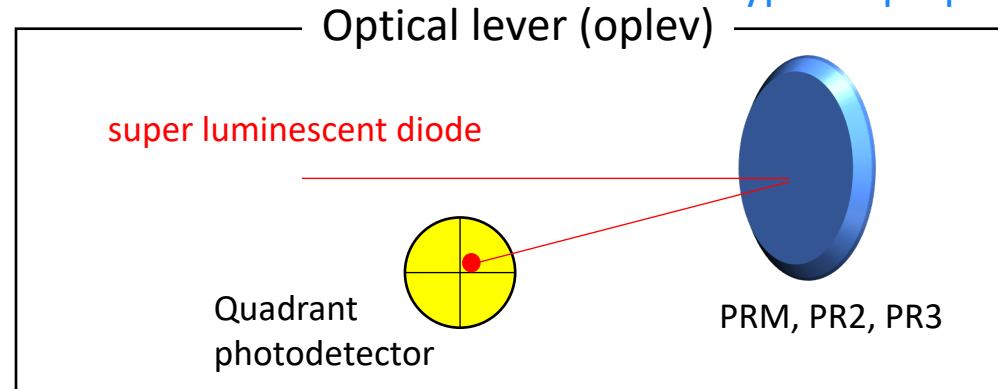


- **Type—Bp Oplev**

- Oplev sensors are used for local damping of resonant motion of Type-Bp suspensions (PRM, PR2, PR3) in pitch (P) and yaw (Y) on the mirror stage
- Transfer function from oplev witness P and Y to DARM was measured (klog 13498)
- Contribution to DARM is estimated by the transfer function x online oplev witness on Apr 12
- Note that there may be overestimate the level together with the PRCL to DARM contribution



Type—Bp oplev



- **Acoustic Noise**

- Evaluated by the PEM injection test.

$$S_{\text{PEM}}(f) = \int [R(f, f') \times P(f')] df'$$

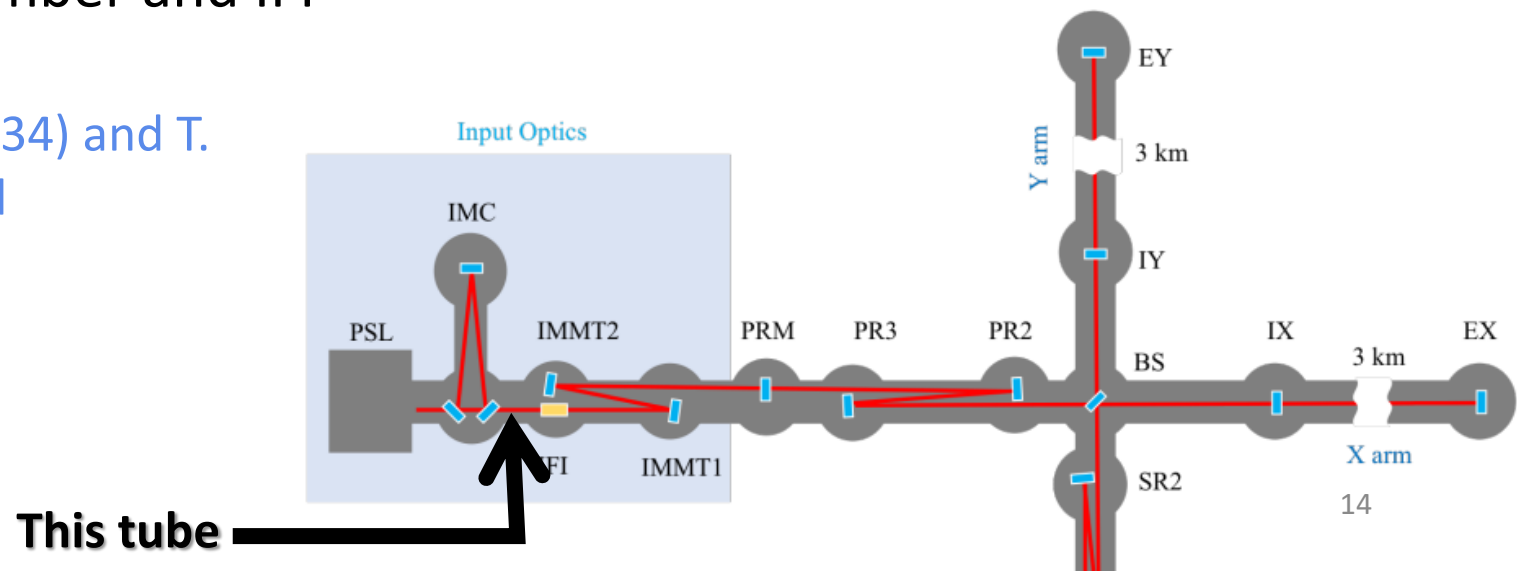
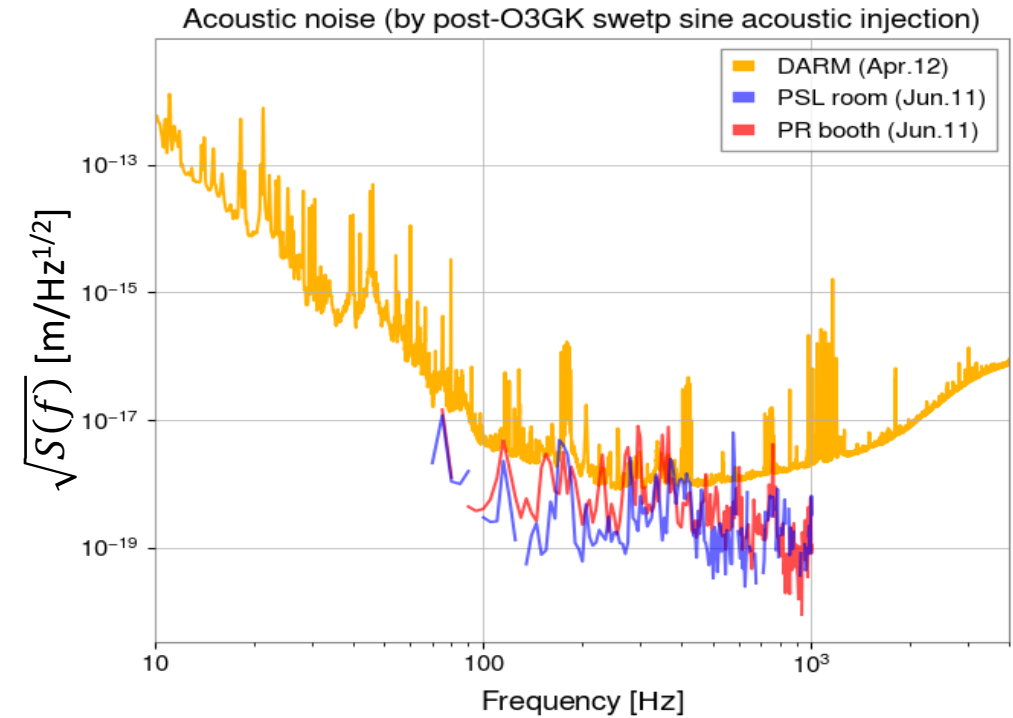
$S_{\text{PEM}}(f)$: Acoustic noise in DARM PSD

$P(f')$: Acoustic field PSD

$R(f, f')$: Response function

- The most effective point was the beam-tube between the IMC chamber and IFI chamber.

- See T. Yokozawa (abstract ID34) and T. Washimi (abstract ID41) and [arXiv:2012.09294](https://arxiv.org/abs/2012.09294)



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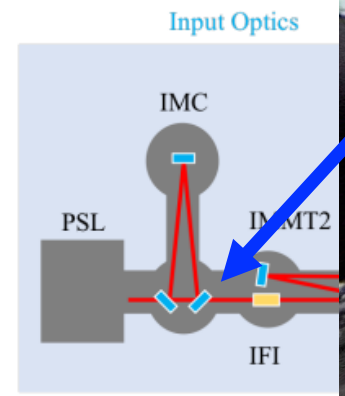
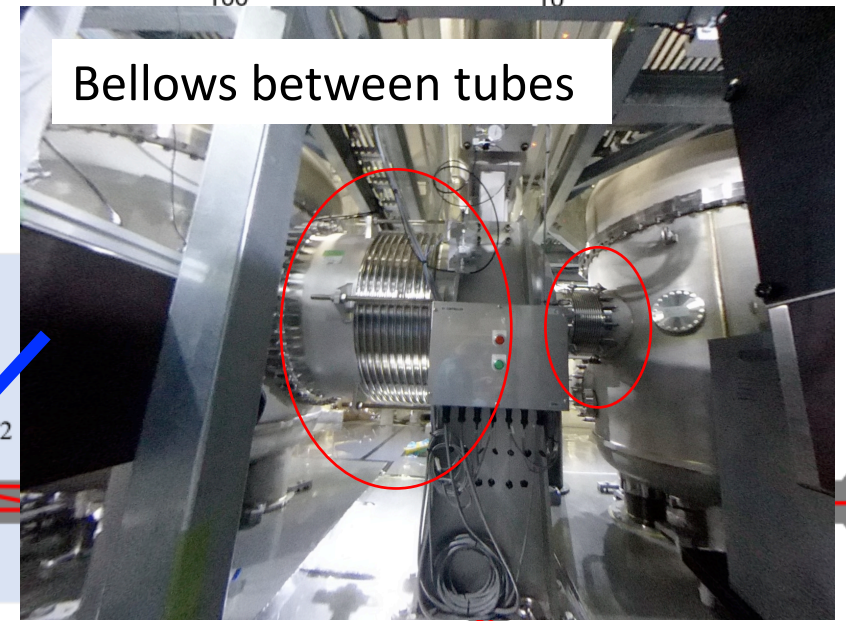
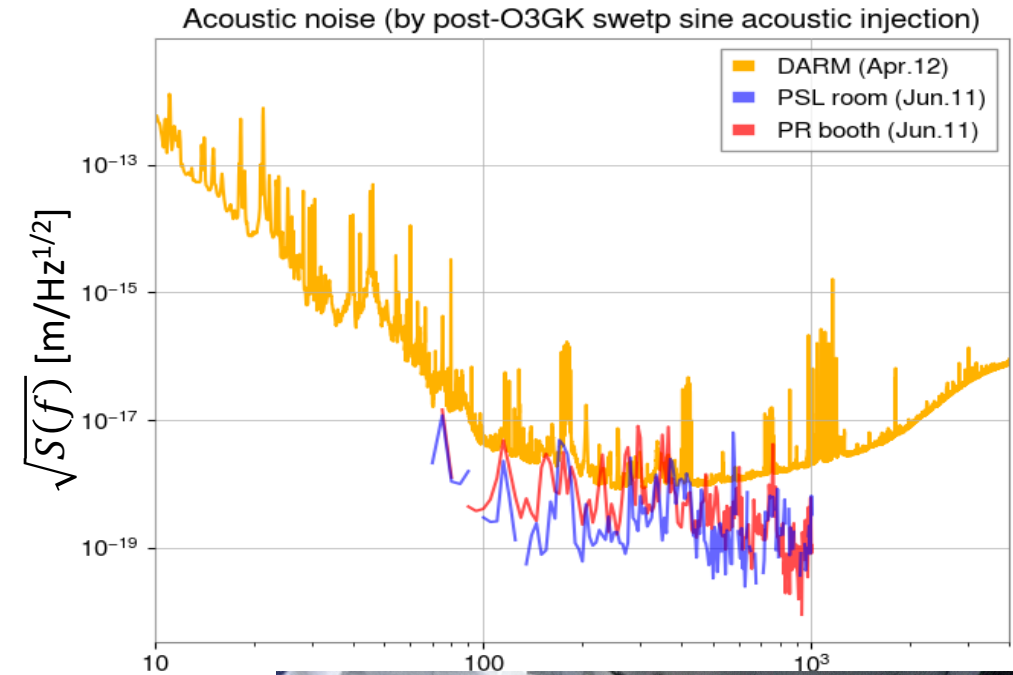
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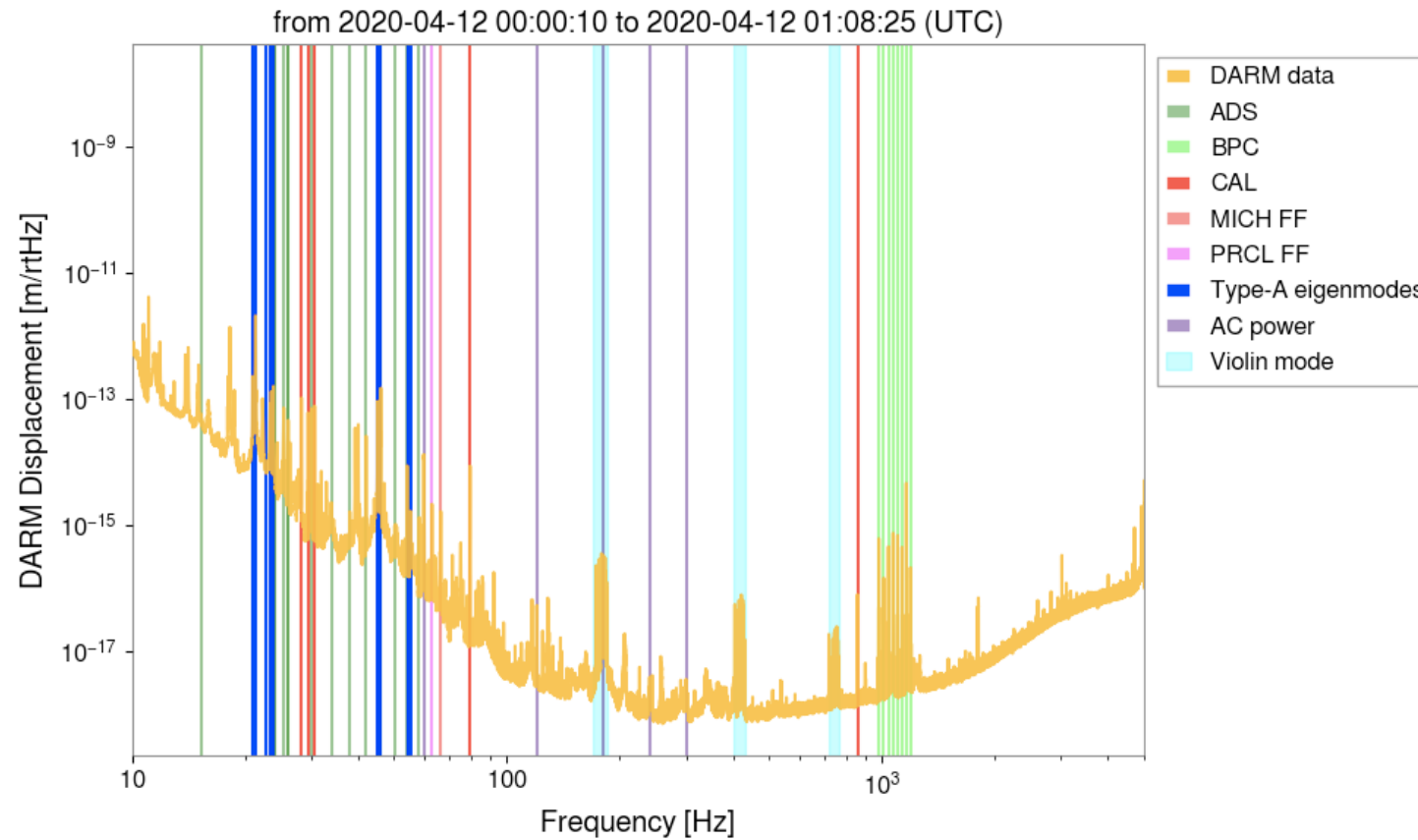
$R(f, f')$: Response function

- The most effective point was the beam-tube between the IMC chamber and IFI chamber.

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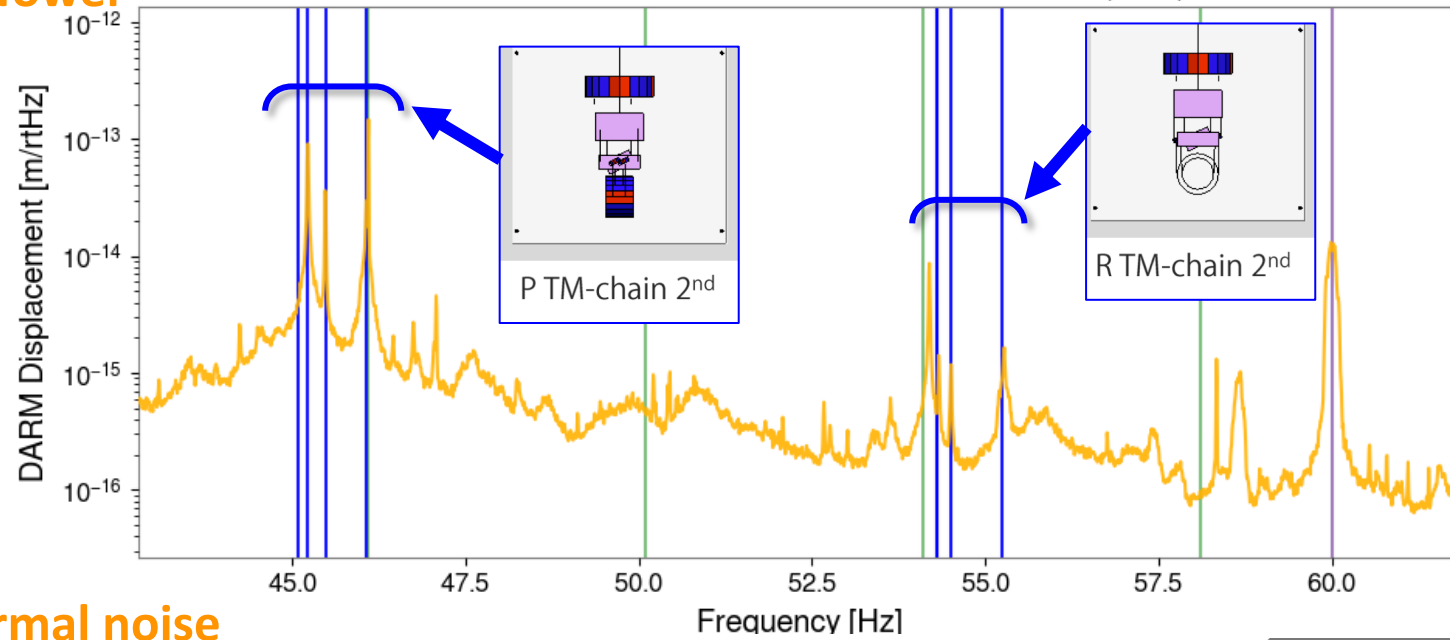
- Line Noise



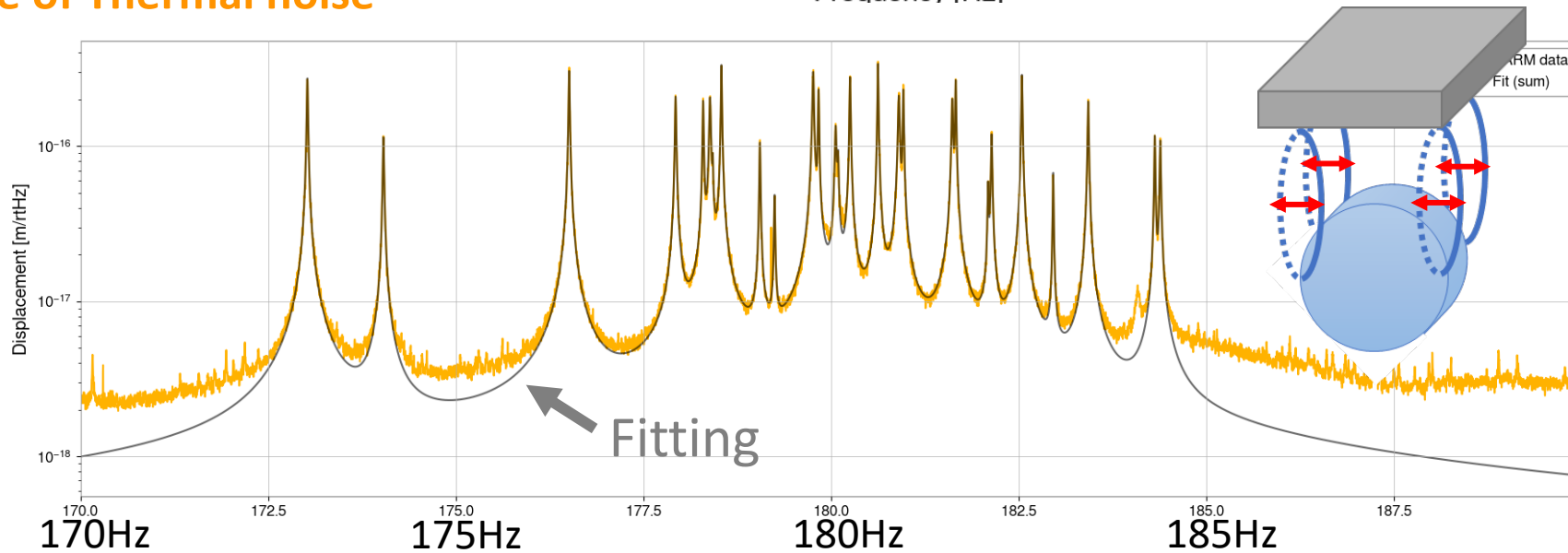
Identified Lines	Know (injected) Lines
Violin modes of suspensions	Alignment Dither System (ADS)
Other Type-A eigenmodes	Beam Position Centering (BPC)
AC power line	DARM Calibration (CAL)
	Feed Forward of PRCL/MICH (MICH FF, PRCL FF)

- Line Noise of VIS Eigenmodes

Type-A Suspension Tower



Violin mode of Thermal noise



Summary

- We evaluated noise contributions on the KAGRA sensitivity during O3GK
- Now almost all dominant noise sources are understood
 - Remaining noise sources
 - Frequency noise
 - TypeB control noise
 - OMC dark noise (minor modification necessary)
- Next step is writing a paper. Target journal is Progress of Theoretical and Experimental Physics (PTEP)